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On detection of a wave age dependency for the sea surface roughness

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Abstract

The wave age dependency of the non-dimensional sea surface roughness (also called the Charnock parameter) is investigated with data from the new field measurement program at Rødsand in the Danish Baltic Sea. An increasing Charnock parameter with inverse wave age is found, which can be described by a power law relation of the form proposed by Johnson et al. (1998) and others.

Friction velocity is a common quantity in both the Charnock parameter and wave age. Thus self-correlation effects are unavoidable in the relation between them. The significance of self-correlation is investigated by employing an artificial 'data' set with randomised wave parameters. It is found that self-correlation severely influences the relation. For the Rødsand data set the difference between real and randomised 'data' was found to be within the measurement uncertainty. By using a small sub-set of the data it was found that the importance of self-correlation increases for a narrower range of wave age values. This supports the conclusion of Johnson et al. (1998), that due to the scatter and self-correlation problems the coefficients of the power law relation can only be obtained from the analysis of an aggregated data set with a wide wave age range combining measurements from several sites.

The dependency between wave age and sea roughness has been discussed extensively in the literature with different and sometimes conflicting results. A wide range of coefficients has been found for the power law relation between the Charnock parameter and wave age for different data sets. It is shown that self-correlation contributes to such differences, since it depends on the range of wave age values present in the data sets. Also, data are often selected for rough flow conditions with the Reynolds roughness number. It is shown that for data sets with large scatter this

can lead to misleading results of the relation of wave age and Charnock parameter. Two different methods to overcome this problem are presented.

1 Introduction

The momentum transfer from the marine atmospheric boundary layer to the wind driven water waves is important for all processes of air-sea interaction, such as wind wave growth, storm surges and atmospheric circulation. It depends on the aerodynamic sea surface roughness, which is therefore one of the most important quantities for the description of the physical processes on both sides of the air-sea interface.

Using dimensional arguments, Charnock (1955) suggested that the dimensionless sea roughness gz_0/u_*^2 (also called the Charnock parameter z_{ch}) is constant, where g is the gravitational acceleration, z_0 the sea surface roughness and u_* the friction velocity. Various field measurements showed that this is a reasonable concept for open ocean sites, except for very low wind speeds (<3-4 m/s), although some increase of Charnock parameter with wind speed has been found (see e.g. (Yelland and Taylor, 1996)). For sites near the coast the Charnock parameter has been found to vary from site to site. Thus, z_{ch} is not a constant, but depends on other geophysical parameters.

It has been argued that these other parameters are properties of the wave field, i.e. that the sea surface roughness is not only dependent on wind speed, but also on the wave field present, which in turn is governed by wind, fetch and water depth. Different attempts have been made to establish a relationship between the sea surface roughness and different properties of the wave field like wave height, wave steepness or wave age (e.g. Hsu, 1974, Donelan, 1990, Smith et al., 1992, Taylor and Yelland, 2001).

However, though it is general consensus that the sea surface roughness depends on the wave field, the quantities suitable for description of this dependence are still a subject of controversy.

Most authors have tried to improve the description of the sea surface roughness by a parameterisation of the Charnock parameter with wave age (e.g. Smith et al. (1992), Donelan et al. (1993), Johnson et al. (1998)). The latter group (hereafter called JHVL98) showed that under specific conditions (discussed in section 2.5) the Charnock parameter only depends on wave age. They describe this dependence with a power law between the Charnock parameter (or normalised sea surface roughness), z_{ch} , and the inverse wave age, u_*/c_p , in the form

$$z_{ch} = A \left(\frac{u_*}{c_p} \right)^B \quad (1).$$

From an empirical fit to measurements from RASEX together with other previously measured data sets they find the coefficients $A=1.89$ and $B=1.59$. One of the main problems in these results was the conflicting, apparent trend of decreasing Charnock parameter with inverse wave age in the RASEX data set taken alone (see also Taylor and Yelland (2001)).

The problem with this kind of scaling is that the two quantities z_{ch} and wave age, between which a functional relationship is proposed, are not independent of each other. This can lead to self-correlation problems, i.e. the functional relationship might be distorted or even determined by the common scaling variable. A theoretical analysis of the self-correlation problem has been presented by Hicks (1978) and specifically for the question of wave age dependent Charnock parameter by Smith et al. (1992). The latter group concluded that self-correlation had an influence on the results of the HEXOS data. JHVL98 generalised that this will always be the case for a

given site, where the fetch range is limited. They concluded that the combination of data from several sites is necessary to minimise self-correlation. This conclusion is also supported by a recent study by Drennan et al. (2003).

In the present paper we follow the JHVL98 approach with three principal aims:

1. To test the relation proposed by JHVL98 with a new, independent data set.
2. To investigate the influence of self-correlation on the relation.
3. To contribute to an understanding of the reasons for the conflicting results found by JHVL98 and in the literature (see e.g. Toba et al. (1990), Drennan et al. (2003), Maat et al. (1991)) by investigating how self-correlation and the data analysis method could influence the resulting trend.

The plan of the paper is as follows: In section 2 the Rødsand field measurement program is presented and the preparation of the measured data described. In section 3 these data are analysed in different ways. The results are compared with each other and with published results. The influence of self-correlation on the relation is investigated in section 4. The data analysis method is discussed in section 5 to gain a better understanding of the relationship between Charnock parameter and wave age. In the final section 6 the conclusions of the paper are summarised.

2 The Rødsand field measurement program

2.1 Site

A 50 m high meteorological measurement mast was established at Rødsand in October 1996 as part of a Danish study of wind conditions for proposed offshore wind

farms. Simultaneous wind and wave measurements were performed from April 1998. The mast is situated about 11 km south of the island Lolland in Denmark (11.74596°E, 54.54075°N). The location of the mast is shown in Figure 1. The mast is located in 7.7 m mean water depth with an upstream fetch of 30 to 100 km (and above) from the SE to WNW sector (120°N to 290°N). The water depth slowly increases to an average upstream depth of about 20 to 25 m in this sector. In the NW to N sector (300°N to 350°N), the water depth is relatively shallower (from 1 m to 7 m) and the fetch is smaller (about 10 km to 20 km).

2.2 Instrumentation and Measurements

The instrumentation of the measurement mast is listed in Table 1. Wave and current data are collected simultaneously with several atmospheric parameters. About 5900 half-hourly records with simultaneous wind and wave measurements have been recorded. A more detailed description of the instrumentation and data can be found in Lange et al. (2001).

Cup anemometers

Mean wind speeds and variances are derived from cup anemometers located at three heights (see Table 1). Calibrated instruments of the type Risø P2546a are used. The calibration accuracy is estimated to be +/- 1%. Data are corrected for flow distortion errors due to the structure on which the anemometer is mounted, i.e. the mast and the booms (see section 2.4.2). However, a correction uncertainty remains, and the overall uncertainty of the wind speed measurement with cup anemometers is estimated to be +/- 3%.

Wind vane

A wind vane of the type Risø Aa 3590 is used. The uncertainty of the instrument itself is negligible. However, the adjustment of the orientation of the instrument is difficult in the field and the absolute accuracy is estimated to be about $\pm 5^\circ$.

Sonic anemometer

The sonic anemometer is of the type Gill F2360a and is mounted at 46.6 m height (42.3m from 12/May/99) above MSL (mean sea level). It measures wind speed in three components (x,y,z) and air temperature with a resolution of 20 Hz. Fluxes are calculated after turning the co-ordinate system such that the mean bias in the vertical and crosswind components are zero. Remaining biases were found to be very small (below 1 cm/s) and neglected.

Errors due to flow distortion of the measuring mast have been corrected for (see section 2.4.2), although remaining errors have to be expected especially for friction velocity measurements. Additionally, sonic anemometers experience an array flow distortion, since transducers and struts of the instrument distort the wind flow in the measurement volume. For the horizontal wind speed component flow distortions are corrected with an individual calibration curve supplied by the manufacturer. This is not the case for the vertical wind component. Mortensen and Højstrup (1995) report systematic differences in a field experiment of typically 5% in mean wind speed and 10-15% in friction velocity between different sonic anemometer types. From wind tunnel measurements they find that the errors are dependent on temperature and mean wind direction. However, they state that further investigations are necessary before a correction method can be established. Therefore no attempt has been made to correct the measurements of the sonic anemometer for array flow distortion. The estimated accuracy for the horizontal wind speed component is about $\pm 5\%$. For the friction

velocity derived by eddy-correlation it is +/- 10%. Both errors are expected to contain a wind direction dependent bias.

Additionally statistical errors due to sampling variability have to be considered, which are responsible for the scatter in the data. Using the approximation of Wyngaard (1973) derived from the Kansas data, the expected accuracy for the u_* measurements is about 10% for an eddy-correlation measurement at 45 m height with an averaging time of 30 minutes and a mean wind speed of 10 m/s. It is mainly this sampling variability which is responsible for the unavoidable scatter in the u_* data.

Acoustic wave recorder

Waves are measured by an acoustic wave recorder (AWR), which is a SONAR-type instrument positioned under water on a support structure. The type is the HD-AWR201 from DHI Water & Environment.

The instrument is located about 100 m south-west of the offshore meteorological mast at Rødsand since March 1998. The instrument was placed 3.74 m above the sea bottom; the average water level during the measurement was 7.7 m. The instrument measures the distance from the acoustic transducer to the water surface with a sampling rate of 8 Hz.

The cut-off frequency of the instrument is determined by its spatial resolution (area sampled by the acoustic transducer at the surface) rather than its sampling rate. It is estimated to be about 0.8 Hz. The measured time series of water level fluctuations was passed through a simple filter in order to remove local spikes in the data. A fixed speed of sound (1475 m/s) is used independent of actual water temperature and salinity. Water temperature and salinity ranges have been estimated for the site. They lead to a maximum measurement error of -4% to +1% in the water level value and wave height.

Water current measurement

The water current sensor is a two dimensional electromagnetic sensor measuring the water velocity in x- and y-direction, manufactured by GMI (Geophysical and Marine Instrumentation, Denmark). It is located 5.3 m above the sea bottom. The measurement accuracy of the sensor is estimated to be +/- 2%.

2.3 Derived measured quantities

2.3.1 Friction velocity

Co-variances are calculated from the sonic anemometer measurements. Linear trends remaining in the time series after selection for stationary conditions (see section 2.5) are removed before calculation of the co-variances. Friction velocity is calculated with the eddy-correlation method as:

$$u_* = \left(\overline{u'w'^2} + \overline{v'w'^2} \right)^{0.25} \quad (2)$$

The uncertainty in the friction velocity measurement is estimated to be about +/- 10% as a combination of the general measurement uncertainty of the instrument and a direction dependent error due to flow distortion.

If the direction dependent error coincides with a wind direction dependent distribution of wave ages in the data, this error can distort the trend of sea surface roughness with wave age. This is investigated by comparing the observed trend with the one found in an analysis without using the sonic anemometer, where the friction velocity is derived from the wind speed variance measurement of a cup anemometer.

For near neutral atmospheric stability, friction velocity u_* and standard deviation of the wind speed σ_u are proportional:

$$u_* = \frac{\sigma_u}{C} \quad (3)$$

The constant C is estimated for the Rødsand data set by comparing the standard deviation measured with the cup anemometer at 50 m height and the friction velocity derived from the sonic anemometer at 46.6 m (42.3 m) height. The ratio of both is plotted versus the stability parameter $50/L$ in Figure 2. No dependence on atmospheric stability can be found for the near neutral stability range used. A possible dependence of C on wave age, which could distort the trend of Charnock parameter versus wave age, is investigated in Figure 3. Also here no significant dependence can be found. The mean value for C is 2.42 with a standard deviation of 0.51, which is about 20%. This is in the range of commonly used values: Garratt (1992) quotes 2.4 for flat terrain, Stull (1988) lists values from 2.47 to 2.57.

The measured value for C is used to derive friction velocities from the three cup anemometer measurements. They provide complementary indirect measurements of the friction velocity, which are expected to have no wind direction dependent error.

2.3.2 Neutral wind speed at 10 m height

The measured mean wind speed has been corrected for influences of the atmospheric stability, described by the Monin-Obukov-length L . This L has been determined from the measurements of the friction velocity, u_* , the heat flux, $\langle w'\Theta' \rangle$, and the potential temperature at 10 m, Θ :

$$L = - \frac{u_*^3}{\kappa \frac{g}{\Theta} \overline{w'\Theta'}} \quad (4)$$

The von Karman constant κ is taken as 0.4 and the gravitational constant g as 9.81 m/s^2 . The error in L due to humidity can be neglected since the humidity influence is

to a large degree included in the heat flux measurement of the sonic anemometer, which measures the sound virtual temperature (see e.g. Schotanus, 1983). The stability function Ψ is calculated by the standard approach (see e.g. Geernaert et al., (1986), JHVL98) and the neutral wind speed u_{10n} is derived from the measured wind speed u_{10} by:

$$u_{10n} = u_{10} + \frac{u_*}{\kappa} \Psi\left(\frac{10}{L}\right) \quad (5)$$

Deviations of the measurement height from 10 m due to water level variations have been accounted for by a log-linear wind profile with Charnock sea surface roughness (with $z_{ch}=0.018$) and the measured stability parameter.

2.3.3 Sea surface roughness

For the calculation of sea surface roughness the measurements of friction velocity u_* , either from sonic or cup anemometer measurements (see section 2.3.1), and of the neutral wind speed at 10 m height u_{10n} have been used. The friction velocity has been corrected to its surface value (see section 2.4.1). The roughness length is calculated from the logarithmic wind profile:

$$z_0 = \frac{z}{\exp\left(\frac{u_n(z)\kappa}{u_*}\right)} \quad (6)$$

The dimensionless sea surface roughness or Charnock parameter is defined as:

$$z_{ch} = \frac{z_0 g}{u_*^2} = \frac{g z}{u_*^2 \exp\left(\frac{u_n(z)\kappa}{u_*}\right)} \quad (7)$$

2.3.4 Wave height, wave periods and wave spectrum bandwidth

All wave parameters have been derived from the time series of water elevation measured by the AWR. The significant wave height H_s is derived from the standard deviation of the water level σ by:

$$H_s = 4\sigma \quad (8)$$

Three different wave periods and the bandwidth of the spectrum are derived from the wave spectrum calculated for each 30 minute wave record measured at Rødsand. The wave period at 50% accumulated variance T_{50} has been calculated as

$$T_{50} = 1/f_{50} \quad (9),$$

the mean period T_m as

$$T_m = m_0/m_1 \quad (10)$$

and the mean period based on zero crossing frequency T_z as

$$T_z = \sqrt{m_0/m_2} \quad (11).$$

The bandwidth of the wave spectrum has been found from

$$bw = \log_{10}(f_{75}/f_{25}) \quad (12)$$

In the equations m_n denotes the n'th moment of the spectrum and f_n the frequency at n% variance.

2.3.5 Wave phase speed at peak frequency

The spectral peak frequency f_p is determined from the measured wave spectra. The direct way of finding f_p would be to search for the frequency corresponding to the maximum spectral density. However, this method is very sensitive to noise. Therefore, following JHVL98, the statistically more stable frequency at 50%

accumulated variance f_{50} is determined first and the measured f_{50} is then converted to f_p by using a mean wave spectrum shape.

The JONSWAP spectral model (Hasselmann et al., 1973) is used as shape function to find the average ratio f_{50}/f_p , which best fits the measured spectra. The average values of the parameters for the fitted spectrum are $\gamma=1.58$ (the peakedness parameter), $f_{50}/f_p=1.11$, $bw=0.153$ and $T_m/T_z=1.081$. These compare well with the measured bandwidth and timescale ratio as shown in Figure 4 and Figure 5, respectively.

The phase speed at peak frequency c_p is calculated using the measured water depth and spectral peak frequency f_p in the linear dispersion relation.

2.4 Data corrections

2.4.1 Correction of the wind stress measurement for elevation

To a first approximation it is usually assumed that the flux in the surface layer is independent of height, implying that the friction velocity is constant. However, this assumption is not entirely correct and for near-neutral and stable conditions the friction velocity decreases slightly with height. Since the determination of the sea surface roughness is very sensitive to the value of the friction velocity, this deviation is accounted for in the determination of the surface friction velocity.

Donelan (1990) derives the following expression from an analysis of the horizontal momentum equation at the surface and the top of the boundary layer, when no observed boundary-layer height is available:

$$u_*(z) = \sqrt{u_{*,s}^2 \left(1 - \frac{\alpha_0 f_c z}{u_{*,s}}\right)} \quad (13)$$

where $u_*(z)$ is the friction velocity measured at height z , $u_{*,s}$ is the friction velocity at the surface, $\alpha_0 = \frac{v_g}{u_{*,s}}$ is the ratio of geostrophic wind v_g and $u_{*,s}$ (taken as $\alpha_0 = 12$), f_c the Coriolis parameter ($1.46 \cdot 10^{-4} \sin(\phi)$, with ϕ latitude).

A direct comparison of this equation with measured friction velocities can not be made with the Rødsand data set, since a sonic anemometer is only available at one height. However, friction velocities derived from cup anemometer measurements of wind speed variances at the three heights 10 m, 30 m and 50 m can be compared. The difference between friction velocities derived from cup anemometer variances at 10 m and 50 m height versus stability parameter is shown in Figure 6, the difference between 10 m and 30 m is shown in Figure 7. A height dependence of the friction velocity is observed, which is independent of stability for the near-neutral stability range used. The mean difference over the height difference of 40.1 m is 0.036 m/s (i.e. 0.0009 m/s per meter), over the height difference of 19.6 m it is 0.021 m/s (0.0011 m/s per meter). The mean decrease of friction velocity with height of 0.00071 m/s per meter height difference from equation (13) is consistent with the data for both height differences. The average measured value has been used to derive the friction velocity at the surface from friction velocities derived at different heights from sonic and cup anemometer measurements.

2.4.2 Correction of wind speeds for flow distortion of the measurement mast

At the Rødsand measurement mast, all cup anemometers as well as the sonic anemometer are mounted on booms pointing in the same direction of about 265° . Flow distortion from the measurement mast and the mounting of the instruments leads

to measurement errors. They are obviously very large for situations with direct mast shade and such records (wind directions $85^\circ \pm 35^\circ$) were omitted.

For other wind directions, a linear correction model was used, which was developed by Højstrup (1999) from measurements at a similar mast at the Vindeby site. In order to investigate the effects of flow distortion from the tower at the Vindeby site, anemometers were mounted at opposite sides of the mast at three different levels for a period of seven months. A triangular lattice measurement mast was used with a tower side length of 1.21 m and a boom length (measured from the nearest corner of the tower) of 2.51 m at 7 m height, leading to a boom length to tower side ratio of about 2. At 20 m and 38 m height it was about 2.5 and 4, respectively, with a tower side length of 0.95 m and 0.60 m and a boom length of 2.40 m and 2.32 m, respectively. The boom directions were 50° and 230° .

Taking the ratio of wind speeds on opposite sides of the tower, averaging in direction bins, a similar picture for all three heights (see Figure 8 where only the highest height is shown) can be seen. Also in Figure 8 the result of a simple model (Højstrup, 1999) is shown, assuming that the tower induced flow distortion is linear in wind direction, away from the sectors directly influenced by the wake of the tower. From Figure 8 it is noted that the simple linear model works well outside of the sectors where one of the anemometers is in the wake of the mast and the other anemometer. For the three heights at Rødsand, correction factors of 1.033/0.994 (maximum increase and decrease), 1.012/0.998 and 1.004/0.999 for the three heights 10 m, 30 m and 50 m, respectively, are used for all wind speeds. The factors for 50 m height are also used for the sonic anemometer mean wind speed and friction velocity. These are illustrated in Figure 9 for all three heights.

Flow distortion of the wind speed standard deviation and the friction velocity is assumed to be similar to that of the mean wind speed and the same correction factors are used for a simple correction. This approach is compared with measurements at Vindeby in Figure 10. Ratios of wind speed standard deviations of the two anemometers are shown, similar to Figure 8. A reasonable agreement between model and measurement is found.

2.4.3 Transformation of wind speeds to water following co-ordinates

For the interaction of wind with waves the relevant wind speed is the difference between air and water movement. Wind measurements made from fixed structures, like the measurement mast at Rødsand, therefore need to be corrected for the water current. At Rødsand, the water current is measured at a mean water depth of 2.4 m. Differences between the current at this depth and the surface current have been neglected and all mean wind speeds measured at the mast have been transformed to refer to the moving reference frame of the water surface.

At Rødsand currents are generally slow, usually below 0.4 m/s, and only in some occasions reach values of up to 0.65m/s. Differences in wind speed due to the transformation are for 93% of the records below 2% and for 99% below 5%.

2.5 Data selection

The first step in data selection is the rejection of data from nonstationary situations, i.e. where the ambient conditions change too much during the 30 minutes of the record under investigation. For the most important quantities the change in time is computed for a time period of 30 minutes before to 30 minutes after the averaging period of the record. Time periods with large gradients are rejected. This was done for

wave phase speed, 10 m wind speed, friction velocity and wind direction. Gradients of not more than 20% per hour were allowed for wave phase speed and wind speed, 30% for friction velocity and 40° for wind direction. Due to this selection, 83% of all measured records were rejected.

The second step is to reject measurements where the derived measured quantities can not be calculated. This is the case if the measurement height of the sonic anemometer of about 45 m is above the surface layer. This can lead to friction velocity measurements which can not be transformed to the surface value. As a simple approximation, the height of the surface layer can be estimated as 10% of the boundary layer height z_h , which is estimated by Tennekes (1982) as:

$$z_h = 0.25 \frac{u_{*,s}}{f_c} \quad (14)$$

Using this expression it is found that the surface layer might be shallower than 45 m if u_* is smaller than about 0.2 m/s. Such measurements have been rejected.

The third step is to select only measurements where the conditions required by the theory under investigation are fulfilled. A simple power law relationship between sea surface roughness and wave age can not be expected to exist for situations where other physical quantities play an important role, which are not represented in the power law. This is the case for situations 1. with non-neutral atmospheric stability, 2. with shallow water effects influencing the wave field (apart from the influence of depth on c_p), 3. with a wave field that is not in local equilibrium with the wind and 4. with flow that is not aerodynamically rough.

The condition of neutral atmospheric stratification is satisfied by correcting the measured wind speed for the influence of stability as described earlier. In addition, this correction is limited to a maximum of 3% correction in u_{10n} and data with larger

deviations from neutral stability are omitted. This leads to limits of $-0.5 < z/L < +0.3$ (with $z=50\text{m}$).

The effect of water depth on the Charnock parameter is to some extent included in the wave age dependency since the wave phase speed c_p is changing with water depth. However, for even shallower water other effects like enhanced whitecapping will become important and are expected to have an influence on the Charnock parameter, which can not be described by wave age alone. To avoid such cases, data with wave phase speed c_p (derived from the measurement) less than 90% of the corresponding values for deep water waves are rejected.

The condition of locally generated wind waves is satisfied by selecting cases where the wave spectrum is single peaked. Furthermore, cases with a bandwidth close to that of the fitted JONSWAP spectrum are chosen. Records with a bandwidth of more than 0.25 are rejected (see Figure 4).

For aerodynamically smooth flow the functional relation between the Charnock parameter and inverse wave age is expected to break down since the Charnock parameter may become dependent on the flow roughness Reynolds number. Therefore the analysis has to be confined to wave ages where smooth flow has no influence. In section 5.2 two approaches to ensure this are discussed. After Donelan (1990) the flow is rough if $u_* > 0.1\text{m/s}$, which is automatically fulfilled because of the selection for a minimum surface layer height (see above). The Toba et al. (1990) criterion of $R > R_{cr} = 2.3$ leads to a limit of inverse wave age of 0.05 for the Rødsand data (see discussion in section 5.2). Rather than selecting data for this limit, it is indicated in the appropriate plots and data with inverse wave age below it should be treated with caution.

401 records (7% of the total number of records) are left in the final data set.

3 Observed trend in sea roughness

3.1 Trend of sea roughness with wave age

Figure 11 gives an overview over the data. The Charnock parameter is plotted versus inverse wave age for all half-hourly records.

A bin-averaging method is used for trend investigation. First the data are sorted for the value of the inverse wave age in bins. The bin width is 0.01. Afterwards averages of u_{10n} , u^* and u^*/c_p are calculated for the records in each bin. The bin values of z_{ch} are derived from the averaged parameters for each bin (see section 5 for a discussion of the bin-averaging method). The standard errors of u_{10n} and u^* have been used to estimate a standard error of the bin value of z_{ch} . Figure 12 shows a comparison of the bin values with the wave age dependent relation for the Charnock parameter from JHVL98. Bearing in mind the measurement uncertainties, the agreement is good. However, from the error bars it can be seen that the scatter in the data is too large to allow a quantification of the parameters in a power law. This can only be done by using a data set with larger wave age variation as shown in section 3.4.

Only one bin value is available for inverse wave ages below the flow roughness limit of 0.05, e.g. in the range where the trend might be influenced by smooth flow after the Toba et al., (1990) criterion. The value does not show a significant deviation from the observed general trend.

3.2 Trend obtained from cup anemometer measurements

With a sonic anemometer the wind stress can be measured with the well-established eddy-correlation method. Omnidirectional sonic anemometers as the one used at Rødsand are, however, susceptible to flow distortion errors especially in the vertical wind speed component and therefore in the friction velocity. Flow distortion errors are by their nature wind direction dependent. A concern is therefore that they coincide with a wind direction dependent variation of wave age values due to different fetch lengths. This could distort or even cause the observed trend of sea surface roughness with wave age.

To rule out this threat, the friction velocity has also been derived by an alternative indirect method from cup anemometer measurements (see section 2.3.1). The method requires that the marine boundary layer is in an equilibrium condition. This can be assumed for the data with near neutral stratification and nearly stationary conditions used in this analysis. This method is expected to be less accurate than the direct eddy-correlation method, but has the advantage of ruling out wind direction dependent flow distortion errors.

Data have been analysed as before, only with the friction velocity derived from the cup anemometer at 10 m height instead of that of the sonic anemometer. No selection has been made for low friction velocities, since the measurement height of 10 m can be expected to be always in the surface layer. The resulting data are shown in Figure 13 as Charnock parameter versus inverse wave age. The data have been bin-averaged as described in section 3.1. Figure 14 shows the result in comparison with the result obtained from the sonic anemometer and the relation proposed by JHVL98. The result from the analysis of the cup anemometer data supports the trend found from the sonic anemometer.

3.3 Trend obtained for different fetch lengths

The measurement location experiences fetches in a wide range from 10 km to more than 100 km (see Figure 1). To test a possible dependence of the relation between Charnock parameter and inverse wave age, four wind direction sectors with approximately uniform fetches have been selected (Table 2).

This requires the selection of the data for narrow wind direction sectors. The wind direction dependent flow distortion error of the sonic anemometer would in this case distort the results, since the Charnock parameter is very sensitive to a bias in friction velocity (an error of 8% in friction velocity causes a doubling of the Charnock parameter). Therefore the friction velocity derived from the cup anemometer has been used (see section 2.3.1). The data have been analysed as described in section 3.2.

The bin values of the Charnock parameter are plotted against inverse wave age for each wind direction sector (see Figure 15). The trend of increasing Charnock parameter with inverse wave age is generally confirmed, although with larger variations. These are caused by the low number of measurement data available in each wind direction sector (see Table 2). A systematic variation of the relation with fetch length is not visible, i.e. a dependence of the coefficients of the power law relation between Charnock parameter and inverse wave age on fetch length can not be found.

3.4 Trend obtained for an aggregated data set

The range of inverse wave age available at one measurement site is relatively small (in the Rødsand data set typically $0.04 < u_*/c_p < 0.09$). This, together with the considerable scatter in the data, makes the determination of the parameters of a power law relation unreliable. Following JHVL98, measurement data from different

locations and with a wide range of wave age values have therefore been combined in an aggregated data set. Data compiled in Donelan et al. (1993) have been used.

For each data set the median values of Charnock parameter and inverse wave age have been plotted (Figure 16). The median has been used as an approximation to the bin values from averaged measured quantities, since the measured quantities were not available individually. It can be seen that the result for the Rødsand measurement is close to the trend line proposed by JHVL98.

A comparison with other proposed trend lines in the literature (Toba et al. (1990), Drennan et al. (2003), Maat et al. (1991), Monbaliu (1994), Smith et al. (1992)) is made in Figure 17. It can be seen that a wide range of coefficients has been found for the power law relation $z_{ch}=A(u_*/c_p)^B$. (see Table 3). Some possible reasons for these differences are discussed in the following chapter.

4 Influence of self-correlation

In Hicks (1981) a numerical method is described to investigate the functional relationship introduced by self-correlation. A functional relation is derived from an artificial random ‘data’ set of unrelated values for the input parameters to the analysis. The functional relationship found will solely be a result of the correlation introduced in the analysis. Here the question is if the introduction of a quantity describing the wave field, namely the wave phase speed as the only wave parameter in the relation, leads to a relation between Charnock parameter and wave age, which has physical meaning and is not a mere result of self-correlation.

For this purpose an artificial ‘data set’ has been produced, where the measured values of wave phase speeds are exchanged by random numbers. Instead of a uniformly

distributed probability of the values as proposed by Hicks (1981), the probability distribution is chosen to follow those of the measured data set (Figure 18c). This is done by randomly redistributing the measured data of wave phase speed within the data set. To increase the data volume and improve ‘randomness’ the measured data set has been repeated several times. For friction velocity and neutral 10 m wind speed the actual measurement values are used without change. Figure 18a and b show their probability distributions in the Rødsand data set.

Figure 19 shows the Charnock parameter versus inverse wave age for the random ‘data’. This can be compared with the measured data from Rødsand shown in Figure 11. Clearly the data points from the random data show larger spreading. However, a trend of increasing Charnock parameter for increasing inverse wave age can be found in both figures. This is clearly an undesired influence of the common scaling variable u_* .

The random ‘data’ have subsequently been analysed in the same way as the real data (see previous chapter): The ‘data’ have been sorted according to wave age bins, the input quantities u_{10n} , u_* and c_p have been averaged for each bin and the bin values of the derived quantities z_{ch} and wave age have been found from these averaged values. Figure 20 shows the resulting bin values of the random ‘data’ in comparison with those of the measured data and the trend line from JHVL98. It is obvious that all three trend lines increase for increasing inverse wave age. The trend line of the random data set is the result of self-correlation of the friction velocity u_* . Its difference to the trend line of the measured data is the result of the physical dependency of the Charnock parameter on the wave phase speed c_p . Both trends appear to be different with the one of the random data showing a smaller slope. However, uncertainties in the measured data, as illustrated by the error bars, are too large to allow the difference in trends to

be conclusive, i.e. due to self-correlation not even the existence of a physical dependency between Charnock constant and wave age can be deduced from this data set. This confirms the conclusion of JHVL98, that a trend which is not severely influenced by self-correlation can only be found when an aggregated data set is used. The range of wave age values has to be large enough to allow a statistically significant separation between the observed trend line and the trend line obtained without wave information.

Ideally, the self-correlation should be investigated for the aggregated data set used in section 3.4. The measured quantities of these data sets were not available. Instead, a smaller sub-set of the Rødsand data are used to investigate the effect of different data sets on self-correlation. For this only data with a nearly constant wave phase speed c_p of 6 ± 0.2 m/s have been selected. The analysis of the data as well as the compilation and analysis of a simulated random 'data' set has been repeated and compared with the result of all data (Figure 21). The Charnock parameters found from the subset of measured data with nearly constant c_p is slightly lower, while the steepness of the relation remains largely unchanged. This is different for the randomised 'data'. Obviously, randomising c_p in a data subset where it is nearly constant does not lead to significant changes and the trend of Charnock parameter with inverse wave age for the randomised 'data' is the same as for the measured data, i.e. the relation is completely determined by self-correlation. Using all measured data, e.g. the whole range of c_p values available at this particular site (see Figure 18), the difference between measured and randomised data in the trends of Charnock parameter versus inverse wave age becomes larger. However, as mentioned above the range of c_p values is not wide enough to allow a statistically significant separation of both trends for the Rødsand data set. For a data set with a very wide range of c_p values, which

could be obtained by aggregating data from different sites, it can be expected that the trends of measured and randomised data are more separated. In this way the effect of self-correlation could be separated from the physical dependency between Charnock constant and wave age.

5 Discussion of analysis method

5.1 Bin-averaging

For the dependence of the Charnock parameter on inverse wave age a power law relation is assumed. The coefficients of the relation have to be found empirically by a fit to measured data. A problem arises if the data show a large statistical spreading and one of the scaling groups does not follow a normal probability distribution.

Data of measured Charnock parameters have a large spreading, mainly due to the sampling variability in the u_* measurement. Also, the Charnock parameter depends on physical quantities of u_* and u_{10n} in a highly non-linear way (see equation 7). Therefore it can not be simply averaged and a fit based on a rms-error of z_{ch} does not seem suitable. A simple example: Assuming 3 records with u_{10n} of 10 m/s and u_* of 0.2, 0.3 and 0.4 m/s the z_{ch} values are calculated to 0.000005, 0.001 and 0.03. The average of the z_{ch} values is 0.01. If instead the physical measured quantities are averaged and z_{ch} is calculated from the average u_{10n} and u_* values, the average z_{ch} is 0.001, i.e. an order of magnitude smaller.

To avoid these problems, a bin-averaging method is used instead of a direct fit or an averaging of z_{ch} . The procedure generally consists of two steps: First the data are

sorted for the value of one parameter (sorting parameter) in bins. Afterwards one or several parameters are averaged over all records in each bin (averaged parameters) and derived quantities are calculated from these (bin values). In the resulting bin values the large statistical spreading has vanished and a linear fit can be made to determine the coefficients of the power law relation. For the determination of a power law relation between Charnock parameter and inverse wave age, the inverse wave age is used as sorting parameter. The averaged parameters are the measured quantities u_* , u_{10n} and c_p . The Charnock parameter is then calculated from these averaged values for each bin. As an estimate of the measurement uncertainty, standard errors of z_{ch} are calculated from the standard errors of the averaged quantities.

Figure 22 shows the difference between the fits of a power law relation to the measured Charnock parameters and the bin values. The large difference is obvious. Also shown is the result of a fit to the logarithm of the measured Charnock parameter $\log_{10}(z_{ch})$. It can be seen that this is a good approximation to the bin-averaging method.

In the previous chapter it was found that the trend of the Charnock parameter with inverse wave age is influenced or even determined by the self-correlation due to the variability in u_* , depending on the range of the u_* and c_p values in the data set. Since this self-correlation is part of the relation found from the measured data, it will also differ for different data sets. This partly explains the differences found from different data sets for the coefficients of the power law relation. The effect of different data sets on the relation found is shown again in Figure 23 for three different wind speed intervals. The data have been sorted according to wind speed and inverse wave age in a two-dimensional bin averaging. The small squares show the bin values of Charnock parameter versus inverse wave age for a certain wind speed and inverse wave age

interval. It is found that the relation is steeper for a narrow wind speed interval due to the dominating influence of self-correlation in u_* . Figure 23 also shows how the choice of the sorting parameter can influence the result of the trend investigation. The large squares are the bin values for the three wind speed intervals without sorting for inverse wave age. The different sorting parameter, in this case wind speed, leads to a different apparent trend of Charnock parameter with inverse wave age.

5.2 Rough flow condition

One of the conditions for the dependence of sea surface roughness on wave age alone is that the air flow must be rough turbulent (see JHVL98). If this condition is not satisfied, it can be expected that the sea surface roughness would also depend on the Reynolds roughness number of the flow.

JHVL98 and others (e.g. Drennan et al.,2003) follow Toba et al. (1990) in defining a limiting roughness Reynolds number $R_{cr}=u_*z_0/\nu$ (with ν =kinematic viscosity) for fully rough flow of 2.3. Since the value is important for the selection of data an attempt is made to uncover its origins in the literature. Toba et al. (1990) quote Schlichting (1979), who defines aerodynamically fully rough flow by:

$$\frac{u_* k_s}{\nu} > 70 \quad (15)$$

here k_s is the sand grain size used in experiments in rough pipes by Nikuradse (1933). For other flows this is related to the roughness parameter k by the empirically found formula by Schlichting (1936):

$$5.75 \log_{10} \left(\frac{k_s}{k} \right) = 8.5 - B \quad (16)$$

Concerning the flow of natural winds over the surface of the earth, Schlichting reports findings from Paeschke (1937), who found $B=5$ when the physical height of the vegetation is used as roughness parameter k . This leads to the relation $k_s=4k$ between Nikuradse's sand grain size k_s and the roughness parameter k . The logarithmic profile used by Schlichting:

$$\frac{u}{u_*} = 2.5 \ln\left(\frac{z}{k}\right) + B \quad (17)$$

can be used to relate his roughness parameter k to the surface roughness length z_0 . Inserting the result, $k=7.4 z_0$, and $k_s=4k$ in equation 17 leads to the limiting roughness Reynolds number used by JHVL98 and Toba et al. (1990):

$$R_{cr} = \frac{u_* z_0}{\nu} = 2.3 \quad (18)$$

Kitaigorodskii (1970) takes a similar approach also based on the measurements of Nikuradse (1933) and finds a similar limiting value of 3.0. The many assumptions about the similar behaviour of flow through pipes and in the atmosphere and about the similar effect of sand, vegetation and waves suggest that these values should be used with caution.

In the following it is shown that the application of the roughness Reynolds number as roughness criterion in a data set with large scatter can lead to a misleading impression about the overall trend in a z_{ch} versus u_*/c_p plot depending on the effective fetch of the site. This is caused by the large scatter of the measured sea surface roughness, which enters into the selection criterion as part of the flow roughness.

The rough flow condition can be written in terms of the Charnock parameter as:

$$z_{ch} > R_{cr} g \nu u_*^{-3} \quad (19)$$

where $R_{cr} = z_0 u_* / \nu$ is the critical flow roughness for rough turbulent flow. For growing wind-waves in fetch limited cases in deep water, Kahma and Calkoen (1994) obtained the following relationship:

$$\frac{u_*}{c_p} = 3.08 (gX)^{-0.27} u_*^{0.54} \quad (20)$$

Equations 20 and 21 can be combined to give:

$$z_{ch} > 520.4 R_{cr} g \nu (gX)^{-1.5} \left(\frac{u_*}{c_p} \right)^{-5.56} \quad (21)$$

Equation 23 is the roughness flow condition expressed in terms of the dimensionless sea roughness (Charnock parameter), inverse wave age and fetch. On a z_{ch} versus u_*/c_p plot, this condition filters out all data points below the line given by Equation 23. The number of data points filtered out depends on the effective fetch at the site. This is illustrated in Figure 24 ($R_{cr}=2.3$, $g=9.81\text{m/s}^2$, $\nu=1.461 \times 10^{-5} \text{ m}^2/\text{s}$), which shows the limiting line of equation 23 for different fetch lengths. It can be seen that for typical ranges of z_{ch} and u_*/c_p and short to moderate fetch lengths (<50km) a large amount of data is filtered out, while a relatively small amount of data is filtered out for the longest fetch lengths (>500km).

Figure 25 shows the Rødsand data segregated according to the flow roughness number. A trend of increasing Charnock parameter with inverse wave age can be seen, although with a large scatter in the data. Figure 25 also shows the calculated Reynolds criterion line using equation 23. It is observed that this corresponds closely to the data when an effective fetch of 30 km is used for the site. For this particular case, the average effective fetch was obtained using equation 22 and the measured values of c_p and u_* . Note that the effective fetch is not the same as the physical fetch,

since the former also includes the influence of wind duration and water depth, since equation 22 is only valid for deep water and waves that are not duration limited.

Applying this condition as a selection criterion to the data before bin averaging leads to problems. This is demonstrated in Figure 26, where the influence of the choice of flow roughness limit on the relation of Charnock parameter with wave age is shown. The data have been selected for different choices of the flow roughness limit and thereafter bin averaged. It can be seen that the relation between Charnock parameter and inverse wave age at small inverse wave ages changes drastically for different flow roughness criteria. This shows that for short to moderate fetch lengths, the scatter above the roughness criterion line can present itself as a trend of decreasing z_{ch} with increasing inverse wave age, i.e. can lead to a misleading impression about the overall trend in a z_{ch} versus u^*/c_p plot. This is probably the cause of the similar apparent trend in the RASEX data as reported by JHVL98. It can also be seen that the obtained trend – apart from the mentioned distortion – does not depend on the value used for the selection criterion for the flow roughness.

Drennan et al. (2003) report a different behaviour for data with a low inverse wave age, which leads them to reject data with $u^*/c_p < 0.05$. They attribute this to a difference between growing and fully developed waves. However, the data selection for rough flow is probably another possible explanation.

If it is assumed that the relation between z_{ch} and u^*/c_p is real and the scatter in the data around it is due to measurement variability, the criterion for flow roughness should be applied to the physical relation rather than the scattered data including measurement variability. In Figure 25 it can be seen that the limiting line for the roughness Reynolds number for an effective fetch of 30 km and $R_{cr}=2.3$ crosses the JHVL98 trend line at an inverse wave age of about 0.05. This criterion should therefore be used

by rejecting data with lower inverse wave ages. In this way the distortion of the result due to application of a selection criterion to a scattered data set is avoided.

An approach different from that used by Toba et al. (1990) and Kitaigorodskii (1970) is proposed by Donelan (1990), who summarises open ocean experiments from Smith (1980) and Large and Pond (1981). He distinguishes only between smooth and rough flow and used the friction velocity as criterion for flow roughness:

$$z_0 = 0.11 \frac{v}{u_*} \quad \text{for} \quad u_* < 2(vg)^{1/3} = 0.1 \frac{m}{s} \quad (\text{smooth flow}) \quad (22)$$

$$z_0 = 0.014 \frac{u_*^2}{g} \quad \text{for} \quad u_* > 2(vg)^{1/3} = 0.1 \frac{m}{s} \quad (\text{rough flow}) \quad (23)$$

The limit for u_* is the value where the sea surface roughness for smooth and rough flow are equal. For the Rødsand data this criterion is automatically fulfilled since data with $u_* < 0.2$ m/s have been rejected already to ensure that the sonic anemometer is in the surface layer (see section 2.5).

6 Conclusion

New simultaneously measured wind and wave data from the field measurement program at Rødsand in the Danish Baltic Sea are presented. These data have been used to test the wave age dependence of the Charnock parameter (or dimensionless sea surface roughness). A general trend of increasing sea roughness with inverse wave age is obtained which agrees with the trend found in JHVL98 and similar parameterisations.

However, by analysing a simulated data set of randomly generated wave ‘data’ it was shown that self-correlation severely influences the observed relation between

Charnock parameter and wave age. Uncertainties in the measured data are too large to allow the difference in trends between real and simulated random 'data' to be conclusive. This means that with the Rødsand data set alone, not even the existence of a physical dependency between Charnock parameter and wave age can be proven.

By using a small sub-set of the Rødsand data it was shown that for a data set with a narrow range of c_p the trend lines of real and random 'data' become almost identical. The larger the range in c_p values, the less significant is the influence of self-correlation. In other words, the wave age variation needs to be caused by the variation in c_p , not by the spreading in u_* . We believe that for a data set with a very large range of wave age values the influences of self-correlation and physical dependency can be separated. This supports the basic idea of JHVL98, that a trend, which is not severely influenced by self-correlation, can only be found with an aggregated data set where the range of wave phase speed values is large. Further research is needed here.

From this investigation it becomes clear that the dependence of the Charnock parameter on wave age is less pronounced than what could be expected without taking into account the influence of self-correlation. We therefore expect that, even if the physical nature of the trend can be shown with such an aggregated data set, the improvement of the Charnock relation with a wave age dependent Charnock parameter is limited. Future research should consider also alternative approaches for the parameterisation of the Charnock parameter, e.g. with wave height or wave steepness.

In the literature, different coefficients for the power law between Charnock parameter and wave age have been found for different data sets. Such differences can be expected since for different data sets – and hence different ranges of the quantities u_*

and c_p – different self-correlation relations follow, which lead to different coefficients in the power law relation.

Additionally, it is shown that the roughness Reynolds number criterion often applied to select data with rough turbulent flow can lead to a misleading impression about the trend in the data, since the sea surface roughness is present in both the selection rule and in the quantity under investigation. This is believed to be the cause of the apparent trend of a decrease in Charnock parameter with inverse wave age in the RASEX data as reported by JHVL98. The importance of this distortion varies with the effective fetch length at the site. It is mainly important for short to medium fetch lengths. Two alternative methods to ensure aerodynamically rough flow are discussed, which do not distort the relation. Instead of applying the roughness Reynolds number criterion to the (scattered) data it can be applied to the relationship found. This leads to a limiting inverse wave age, which in the case of the Rødsand data is $u_*/c_p > 0.05$. A different criterion for rough flow is the one by Donelan (1990), who finds a limit of $u_* > 0.1$ m/s for rough flow, by equating the sea surface roughness estimated for rough and smooth flow.

A misleading trend can also be caused by the methods to obtain the parameterisation from the data. Investigation of the bin-averaging method showed that the choice of the sorting parameter in the bin-averaging analysis can lead to an inversion of the observed trend of Charnock parameter with wave age.

To sum up, we conclude that the parameterisation of the Charnock parameter as a function of wave age is fraught with many difficulties, hence one must be cautious in using such a relationship, especially if derived from single site measurements. Some of the difficulties include the influence of self-correlation, selective filtering introduced by the roughness flow condition, and the usually large scatter in the

Charnock parameter itself. Some of the differences found in the literature can probably be explained by these difficulties.

The Rødsand data show an increase of Charnock parameter with inverse wave age in line with most literature results. While the existence of the trend seems clear, the significance of it is not. We find that the importance of the physical dependency in the Rødsand data set is questioned by self-correlation effects, i.e. that the relation is severely influenced by self-correlation. However, our results point to that the self-correlation effects can be reduced by striving for an equally strong variability of the different data entering into the regression procedure and taking effort to avoid for spurious correlation between the parameters, as for example by aggregating data sets as in JHVL98.

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Figure captions

Figure 1: Rødsand measurement site

Figure 2: Ratio of standard deviation measured with the cup anemometer at 50 m height and friction velocity derived from the sonic anemometer at 46.6 m (42.3 m) height versus stability parameter $50/L$; horizontal lines show the mean ratio (2.42) and its standard deviation (0.51)

Figure 3: Ratio of standard deviation measured with the cup anemometer at 50 m height and friction velocity derived from the sonic anemometer at 46.6 m (42.3 m) height versus inverse wave age u_*/c_p ; horizontal lines show the mean ratio (2.42) and its standard deviation (0.51)

Figure 4: Bandwidth of the measured data at Rødsand versus significant wave height; also shown is the bandwidth of the fitted JONSWAP spectrum (0.15) and the bandwidth limit used to select single peaked spectra (0.25)

Figure 5: Ratio of mean period and wave period based on zero crossing frequency of the measured data at Rødsand versus significant wave height; also shown is the timescale ratio of the fitted JONSWAP spectrum

Figure 6: Difference between friction velocities derived from cup anemometer standard deviations at 10 m and 50 m height versus stability parameter; horizontal lines show the mean difference (0.036 m/s), its standard deviation (0.029 m/s) and the mean result of eq. (13)

Figure 7: Difference between friction velocities derived from cup anemometer variances at 10 m and 30 m height versus stability parameter; horizontal lines show the mean difference (0.021 m/s), its standard deviation (0.019 m/s) and the mean result of eq. (13)

Figure 8: Triangles: Binned ratios of wind speed measurements at 38m . Circles: Model results assuming flow distortion linear away from tower wake influence (see also Figure 9); data are from the Vindeby measurement program

Figure 9: Correction for tower flow distortion of wind speed at Rødsand as a function of wind direction with the model by Højstrup (1999). Note that the correction is positive on average, and that the correction diminishes for increasing boom length to tower side ratio

Figure 10: Triangles: Binned ratios of measurements of wind speed standard deviations at 38m . Circles: Model results assuming flow distortion linear away from tower wake influence; data are from the Vindeby measurement program

Figure 11: Charnock parameter versus inverse wave age from Rødsand data

Figure 12: Charnock parameter versus inverse wave age from Rødsand data; bin values with respect to wave age are shown with their standard errors in comparison with the empirical fit of JHVL98

Figure 13: Charnock parameter versus inverse wave age from Rødsand data with friction velocity derived from cup anemometer measurement

Figure 14: Charnock parameter versus inverse wave age from Rødsand data with friction velocity derived from cup and sonic anemometer measurements; bin values with respect to wave age are shown with their standard errors in comparison with the empirical fit of JHVL98

Figure 15: Charnock parameter versus inverse wave age from Rødsand measurement bin averaged with respect to wave age; data from four wind direction sectors with different fetches are shown together with the empirical fit of JHVL98

Figure 16: Scatter plot of averaged Charnock parameter versus inverse wave age for several data sets and comparison with the empirical fit of JHVL98

Figure 17: Comparison of averaged Charnock parameter versus inverse wave age for several data sets with proposed empirical relations

Figure 18: Probability distributions of u_* , u_{10n} , and c_p in the measured Rødsand data

Figure 19: Charnock parameter versus wave age from simulated random 'data'

Figure 20: Wave age bin values of Charnock parameter versus inverse wave age from the Rødsand measurement and the simulated random 'data'; also shown is the JHVL98 relation

Figure 21: Comparison of wave age dependency of Charnock parameter for all data and a data subset with wave phase speed c_p of 6 ± 0.2 m/s; shown are results from the Rødsand measurement and simulated random 'data' sets

Figure 22: Comparison of methods to fit a power law relation between Charnock parameter and inverse wave age to measured data

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Figure 26: Charnock parameter versus inverse wave age for different flow roughness selection criteria

Table captions

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Table 2: Selected wind direction sectors with approximately uniform fetch

Table 3: Parameter values proposed for the power law relation $z_{ch}=A(u_*/c_p)^B$ in the literature

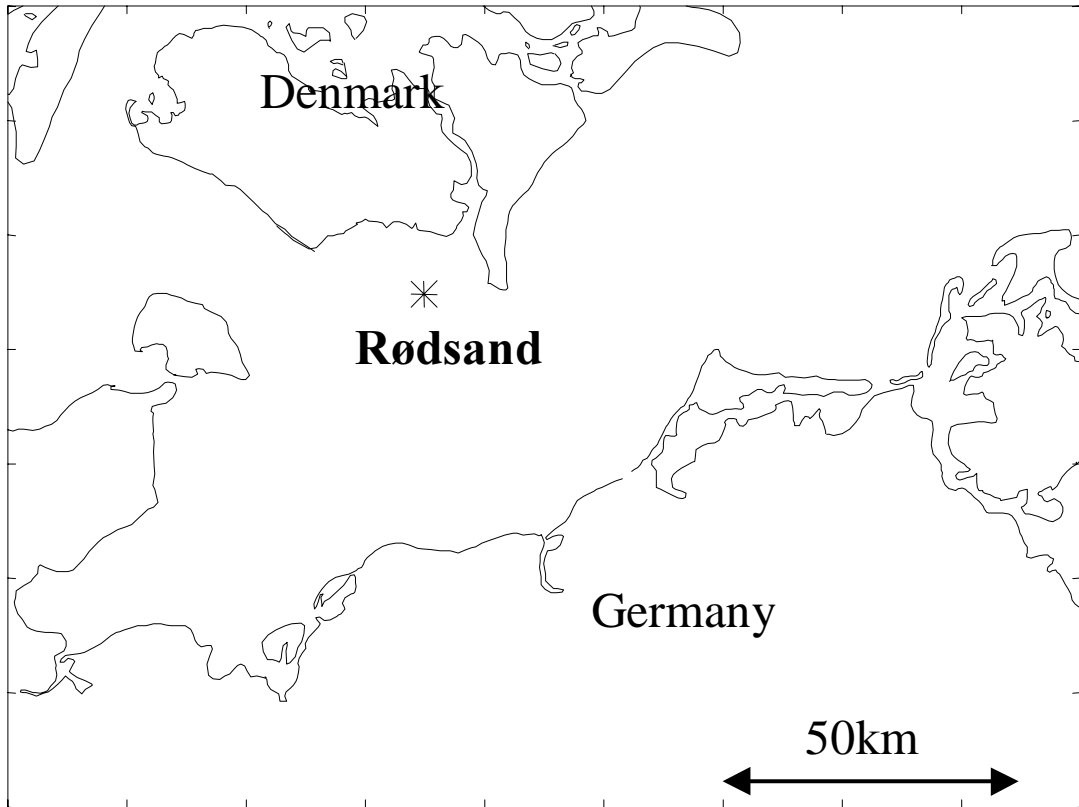


Figure 1: Rødsand measurement site

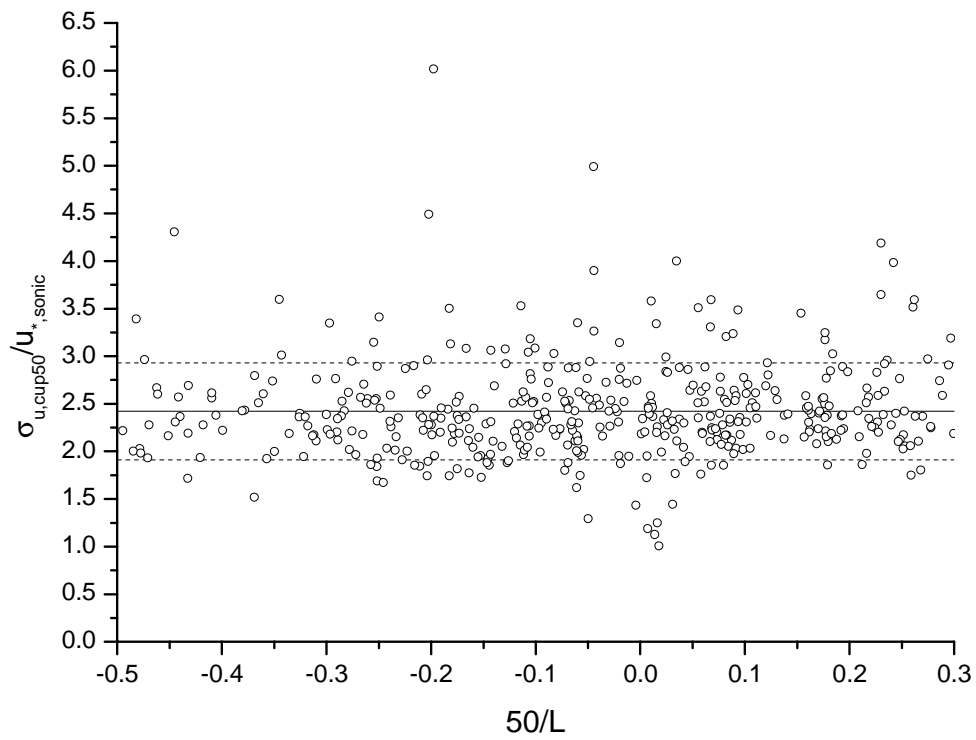


Figure 2: Ratio of standard deviation measured with the cup anemometer at 50 m height and friction velocity derived from the sonic anemometer at 46.6 m (42.3 m) height versus stability parameter $50/L$; horizontal lines show the mean ratio (2.42) and its standard deviation (0.51)

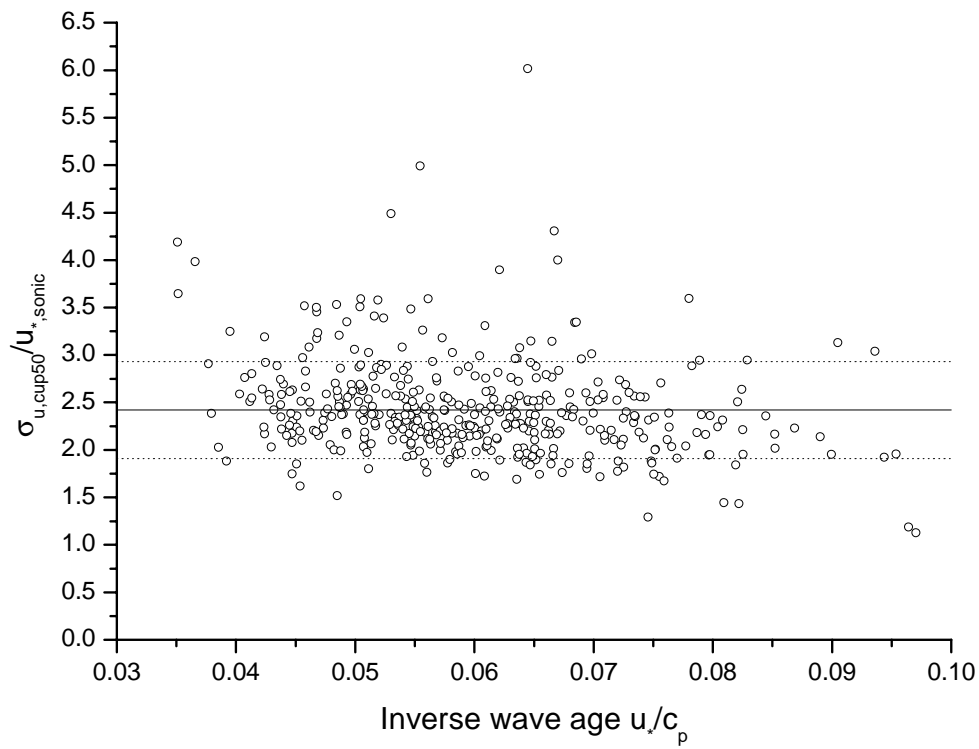


Figure 3: Ratio of standard deviation measured with the cup anemometer at 50 m height and friction velocity derived from the sonic anemometer at 46.6 m (42.3 m) height versus inverse wave age u^/c_p ; horizontal lines show the mean ratio (2.42) and its standard deviation (0.51)*

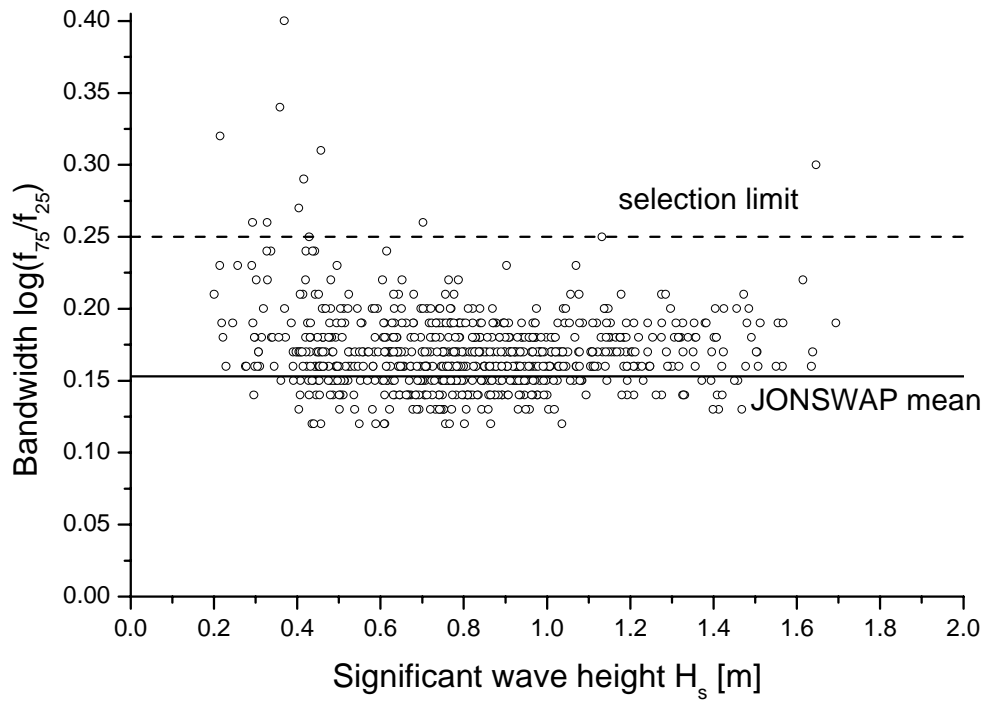


Figure 4: Bandwidth of the measured data at Rodsand versus significant wave height; also shown is the bandwidth of the fitted JONSWAP spectrum (0.15) and the bandwidth limit used to select single peaked spectra (0.25)

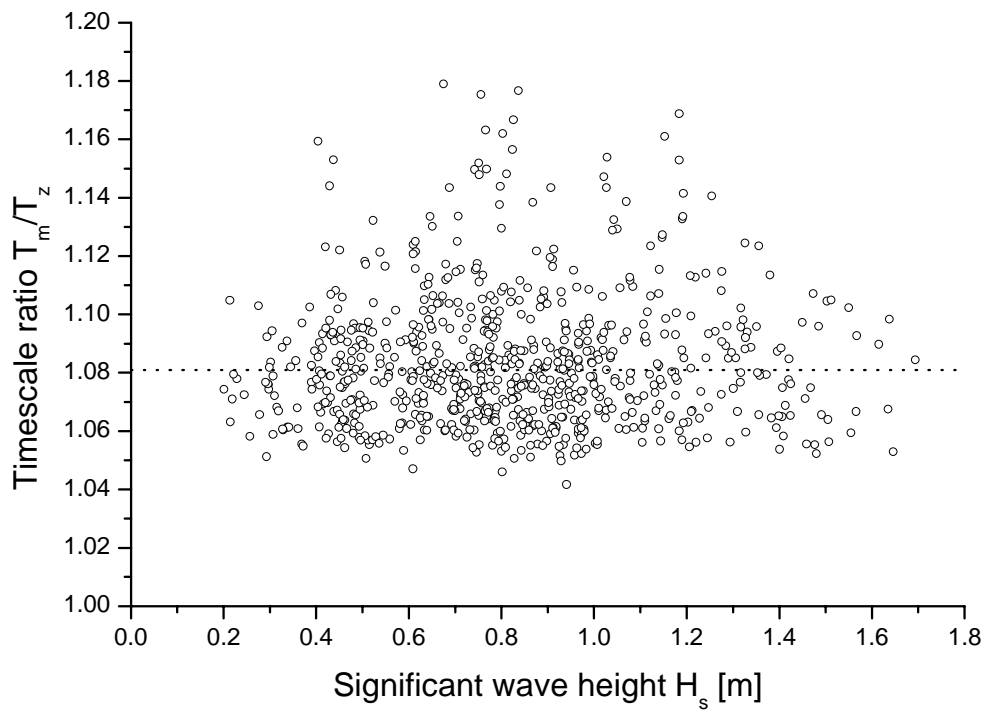


Figure 5: Ratio of mean period and wave period based on zero crossing frequency of the measured data at Rødsand versus significant wave height; also shown is the timescale ratio of the fitted JONSWAP spectrum

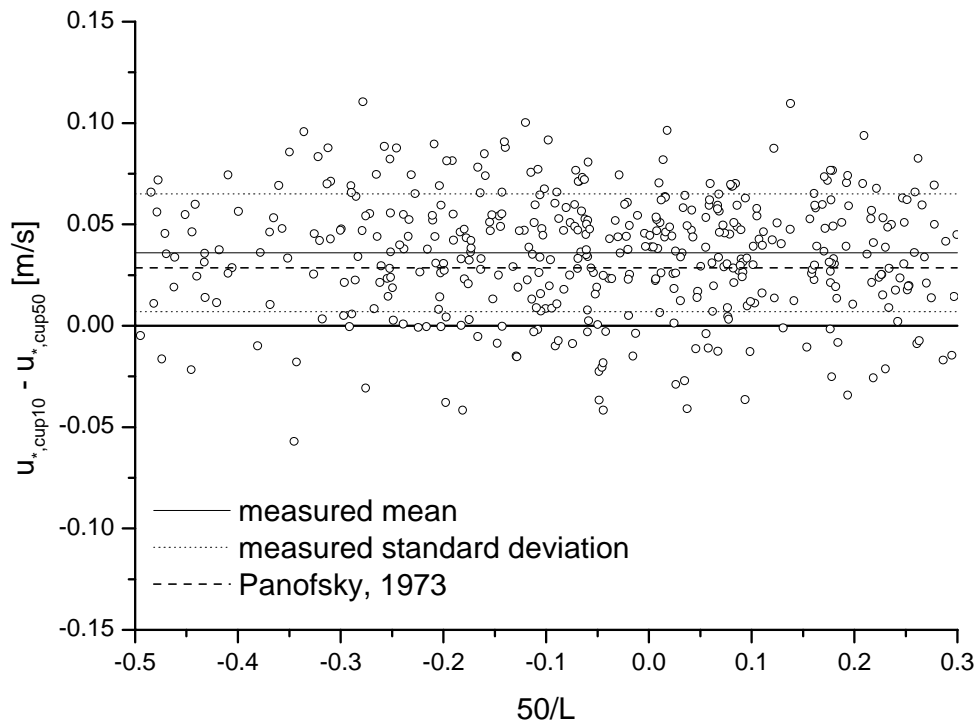


Figure 6: Difference between friction velocities derived from cup anemometer standard deviations at 10 m and 50 m height versus stability parameter; horizontal lines show the mean difference (0.036 m/s), its standard deviation (0.029 m/s) and the mean result of eq. (13)

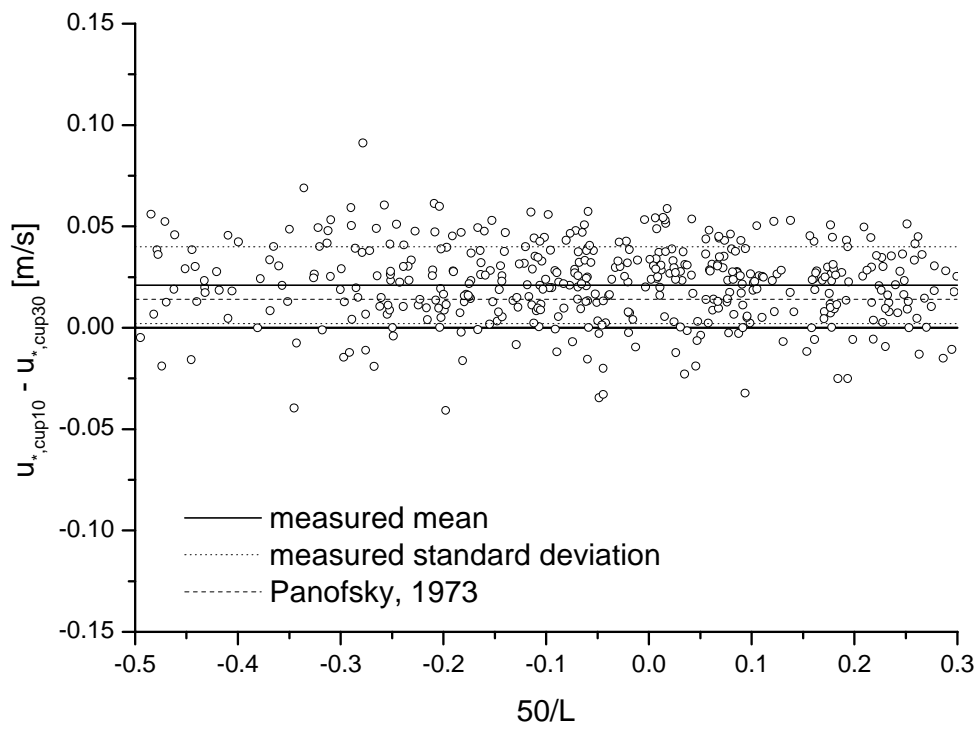


Figure 7: Difference between friction velocities derived from cup anemometer variances at 10 m and 30 m height versus stability parameter; horizontal lines show the mean difference (0.021 m/s), its standard deviation (0.019 m/s) and the mean result of eq. (13)

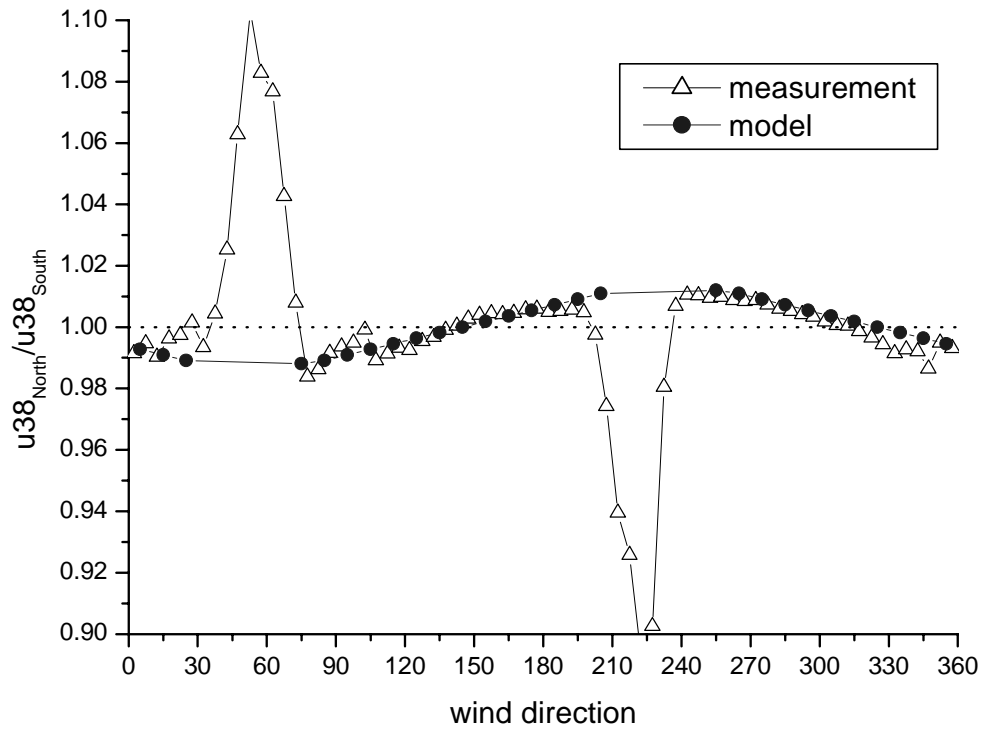


Figure 8: Triangles: Binned ratios of wind speed measurements at 38m . Circles: Model results assuming flow distortion linear away from tower wake influence (see also Figure 9); data are from the Vindeby measurement program

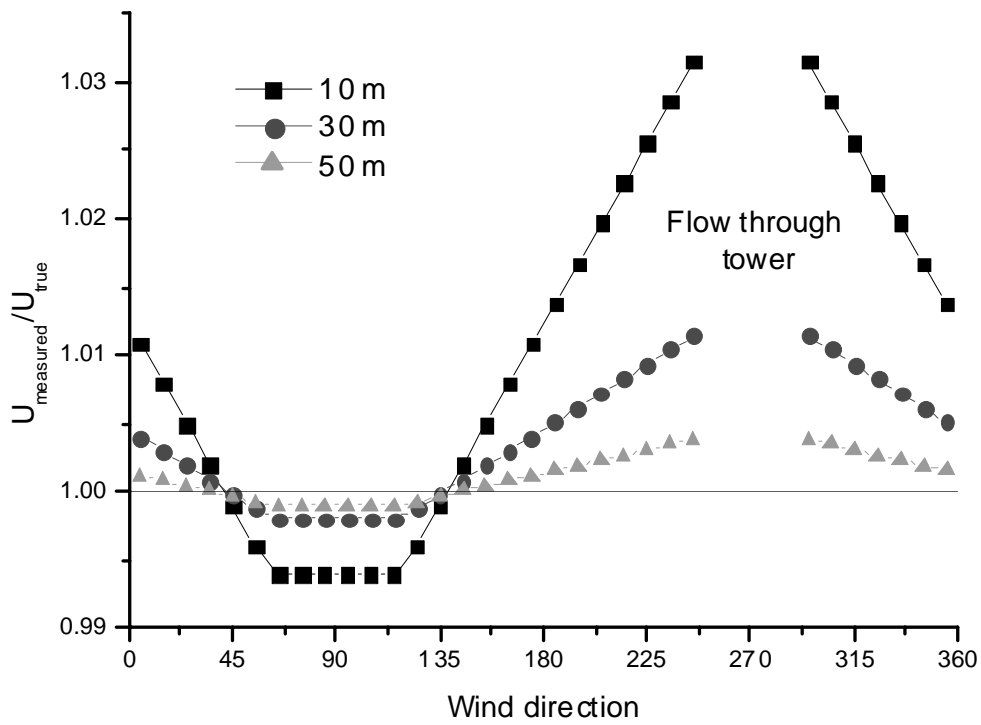


Figure 9: Correction for tower flow distortion of wind speed at Rødsand as a function of wind direction with the model by Højstrup (1999). Note that the correction is positive on average, and that the correction diminishes for increasing boom length to tower side ratio

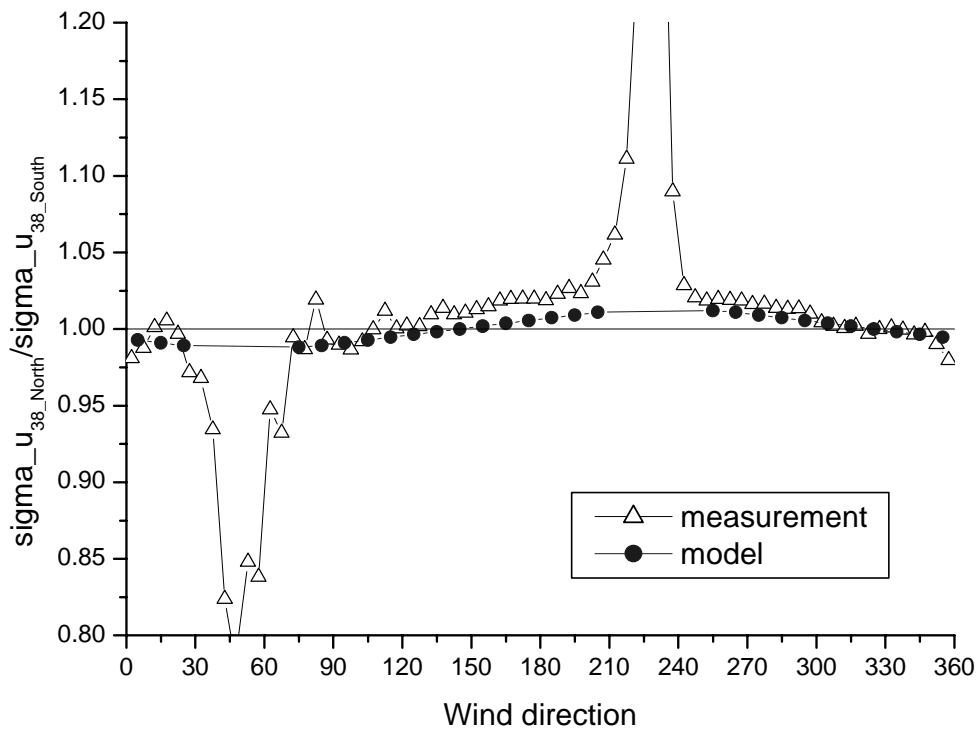


Figure 10: Triangles: Binned ratios of measurements of wind speed standard deviations at 38m . Circles: Model results assuming flow distortion linear away from tower wake influence; data are from the Vindeby measurement program

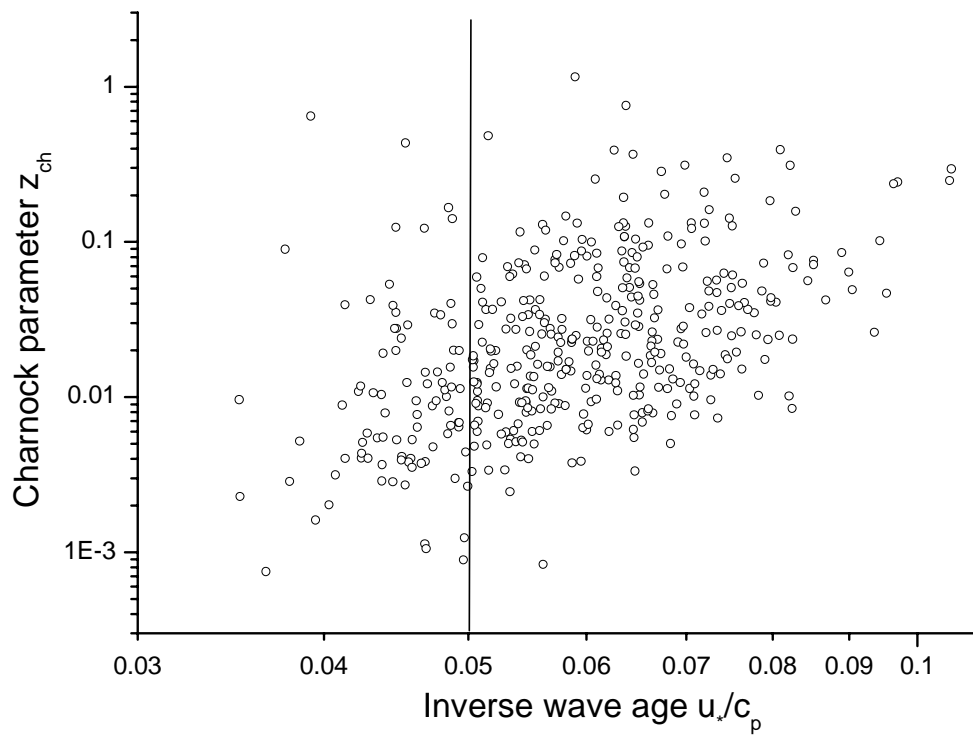


Figure 11: Charnock parameter versus inverse wave age from Rødsand data

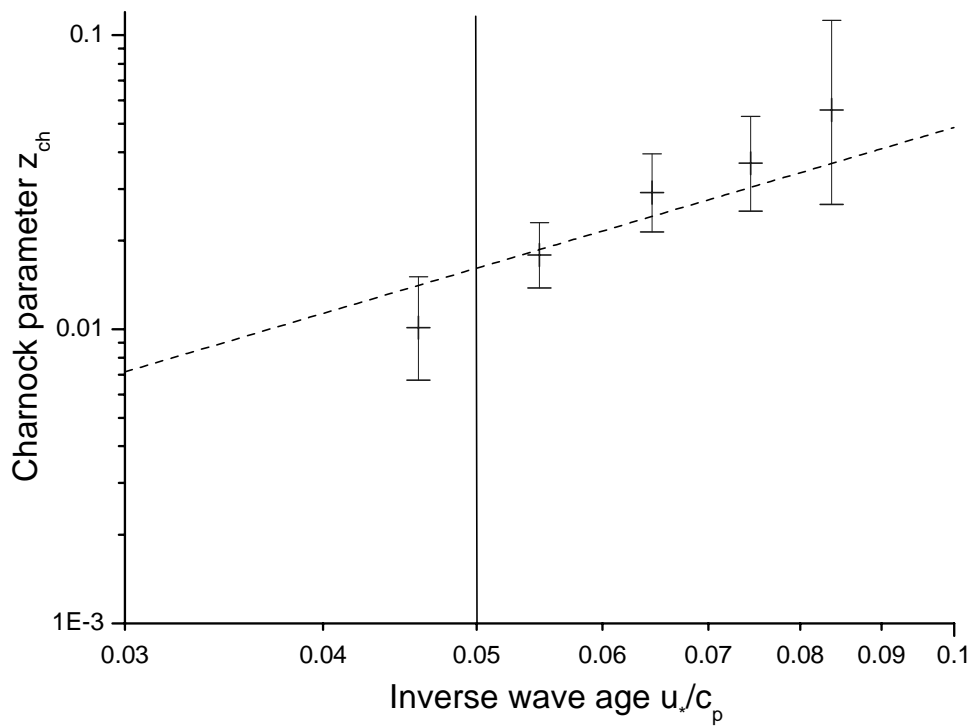


Figure 12: Charnock parameter versus inverse wave age from Rodsand data; bin values with respect to wave age are shown with their standard errors in comparison with the empirical fit of JHVL98

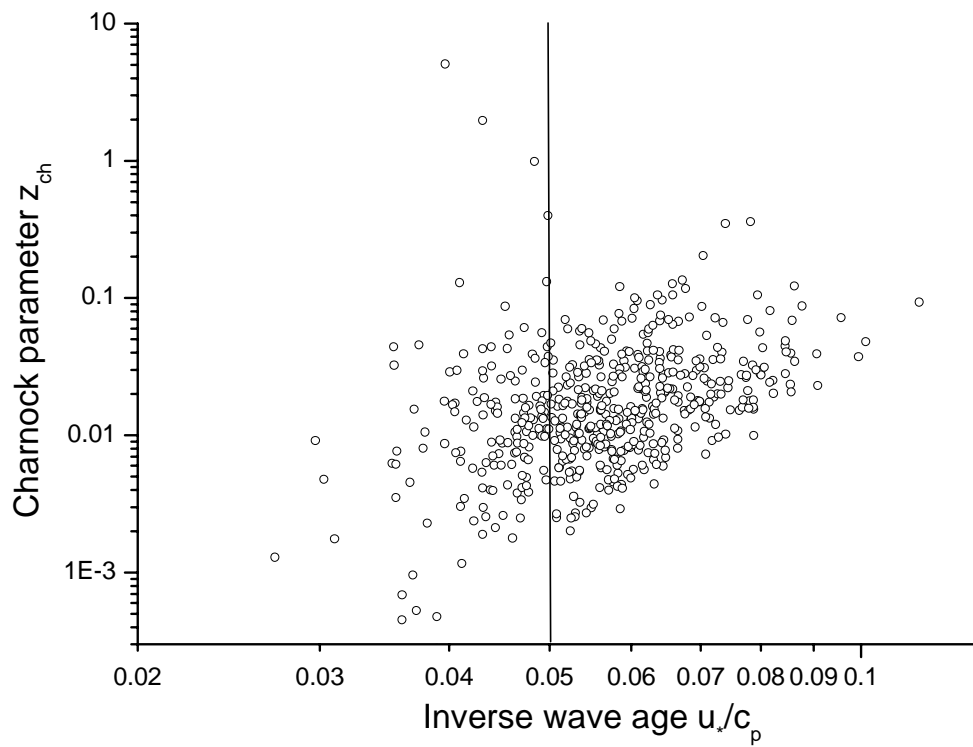


Figure 13: Charnock parameter versus inverse wave age from Rødsand data with friction velocity derived from cup anemometer measurement

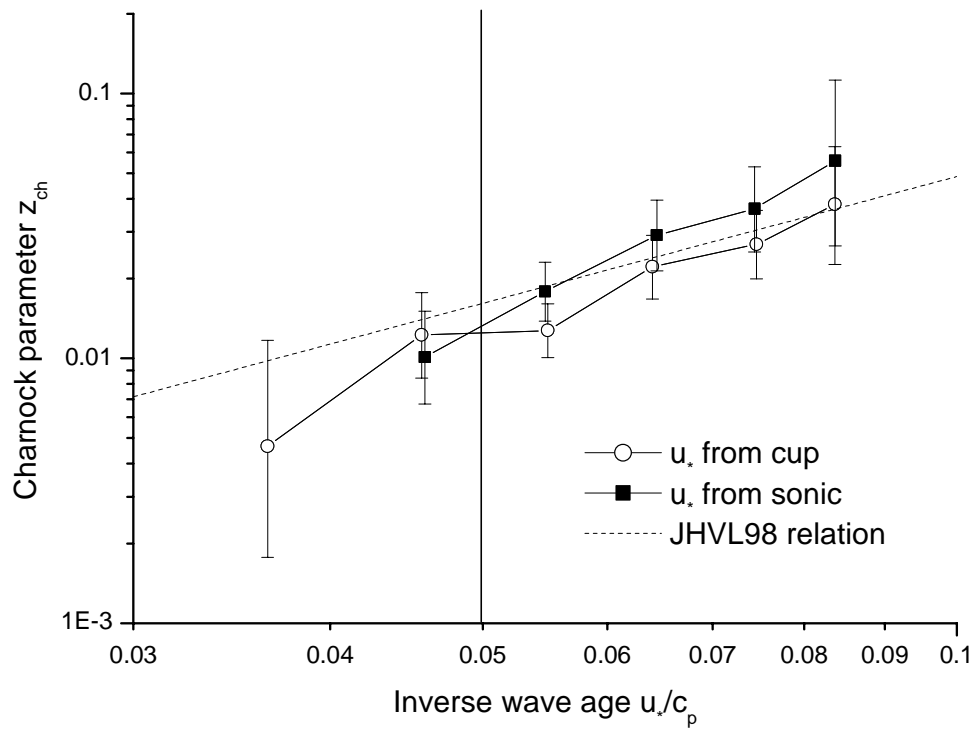


Figure 14: Charnock parameter versus inverse wave age from Rødsand data with friction velocity derived from cup and sonic anemometer measurements; bin values with respect to wave age are shown with their standard errors in comparison with the empirical fit of JHVL98

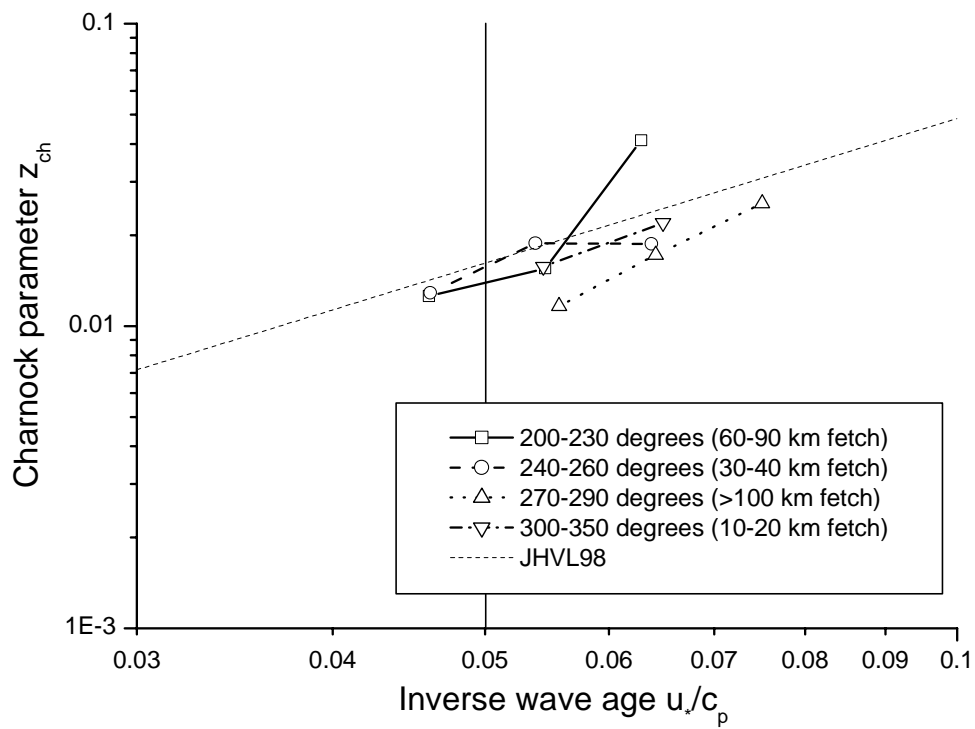


Figure 15: Charnock parameter versus inverse wave age from Rødsand measurement bin averaged with respect to wave age; data from four wind direction sectors with different fetches are shown together with the empirical fit of JHVL98

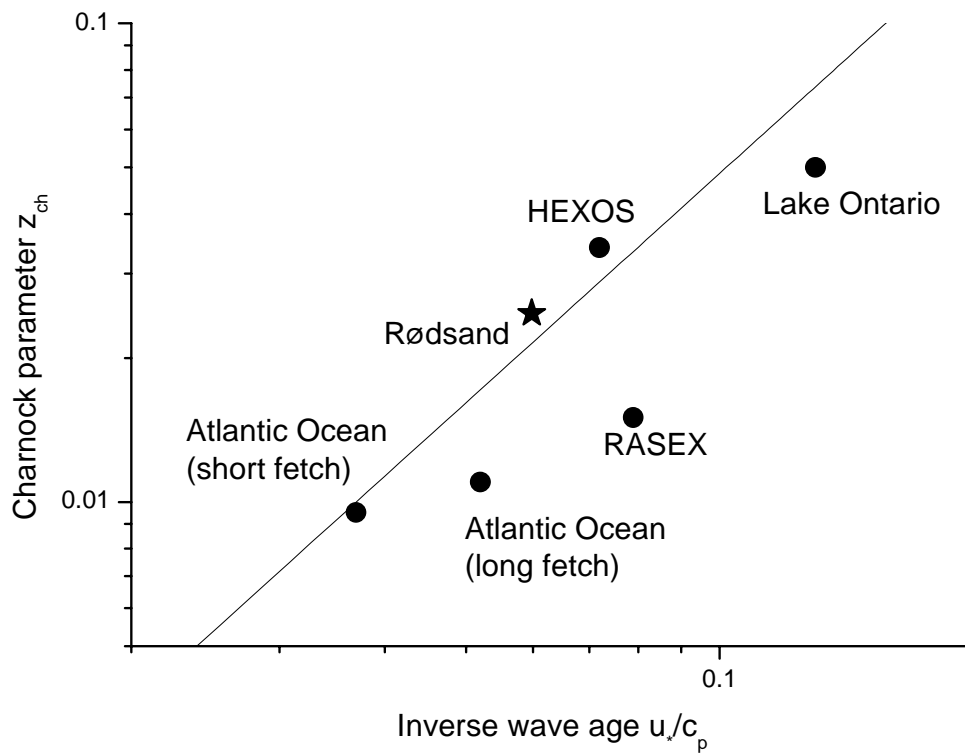


Figure 16: Scatter plot of averaged Charnock parameter versus inverse wave age for several data sets and comparison with the empirical fit of JHVL98

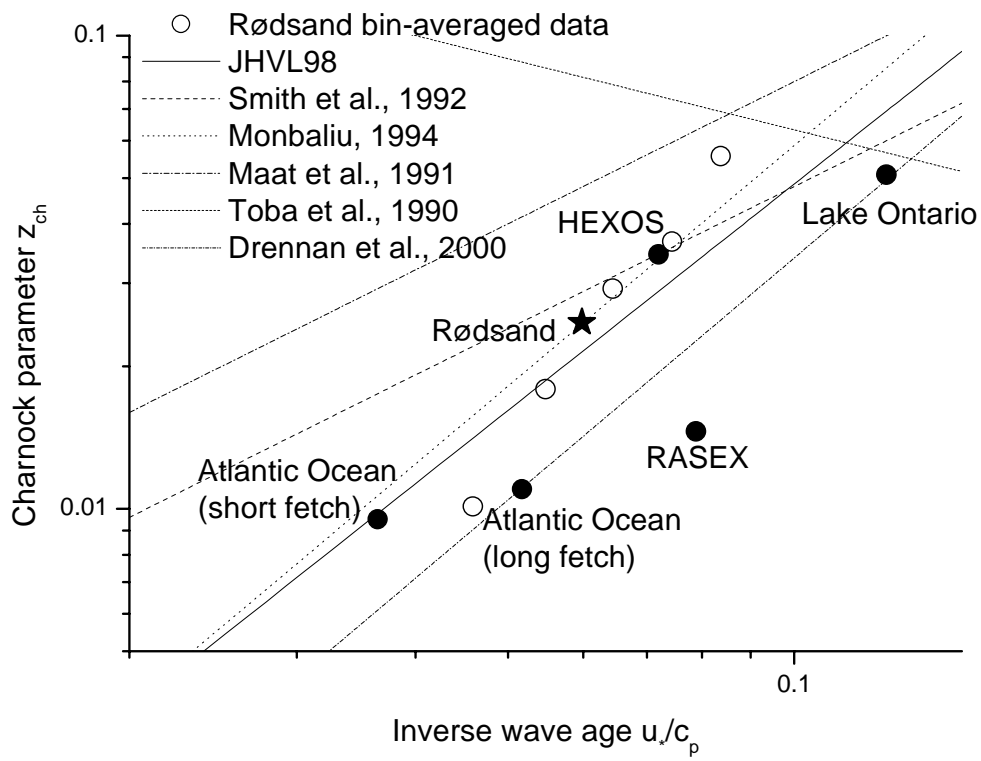


Figure 17: Comparison of averaged Charnock parameter versus inverse wave age for several data sets with proposed empirical relations

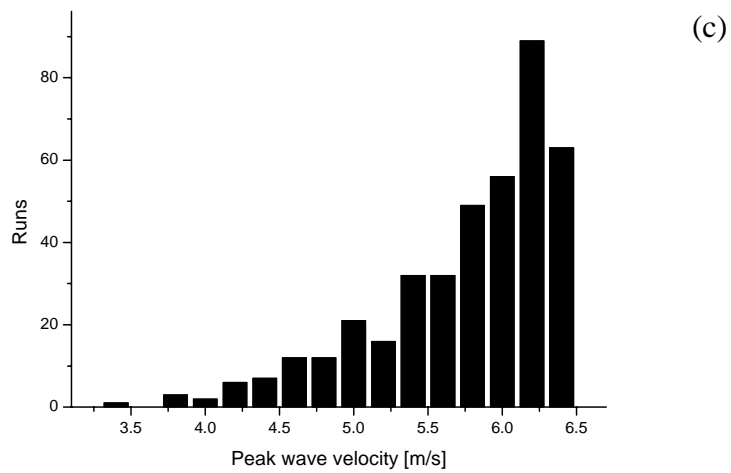
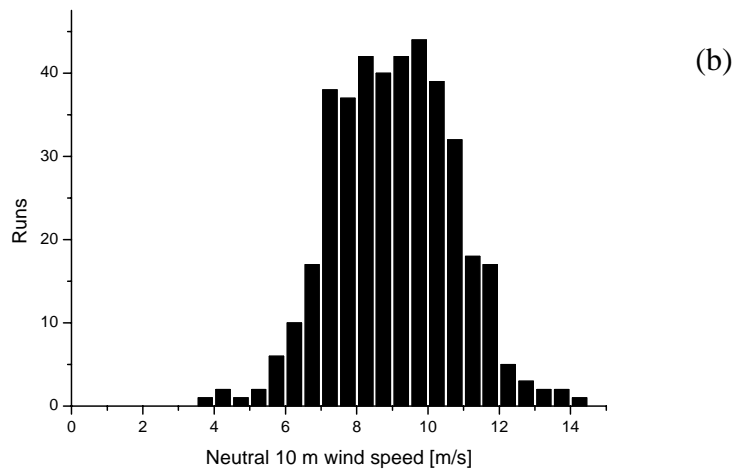
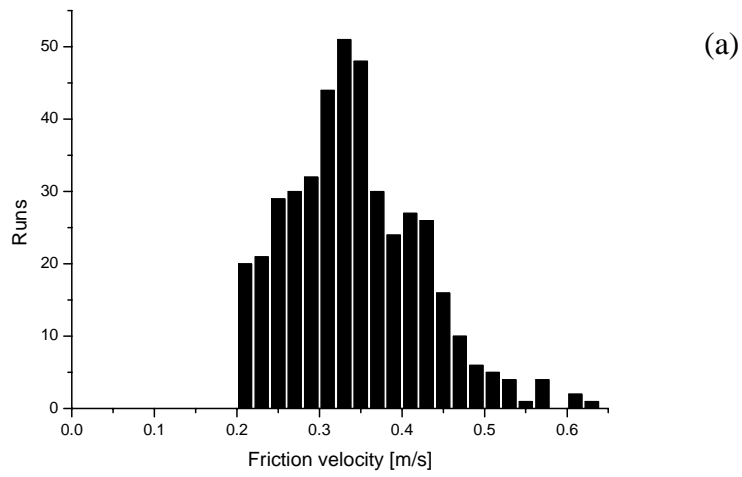


Figure 18: Probability distributions of u_* , u_{10m} , and c_p in the measured Rødsand data

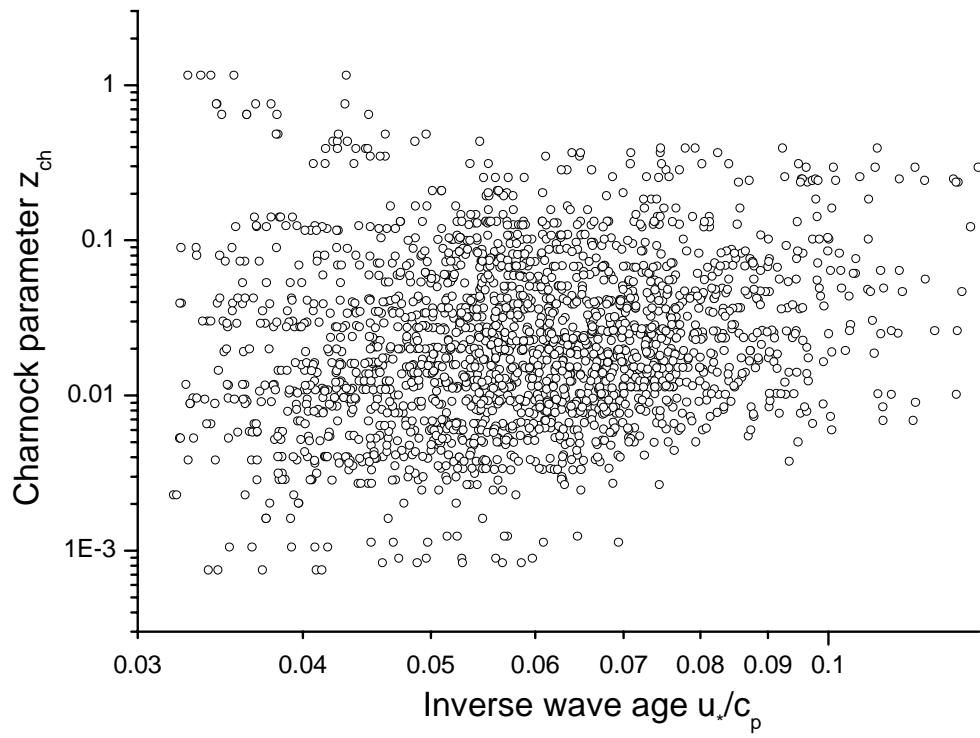


Figure 19: Charnock parameter versus wave age from simulated random 'data'

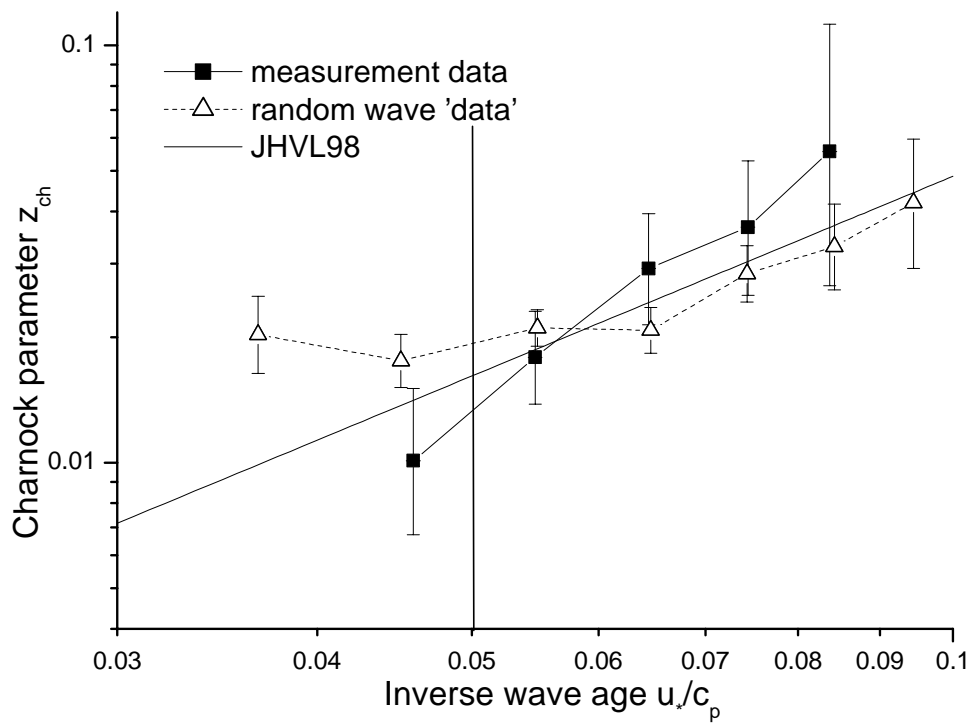


Figure 20: Wave age bin values of Charnock parameter versus inverse wave age from the Rødsand measurement and the simulated random 'data'; also shown is the JHVL98 relation

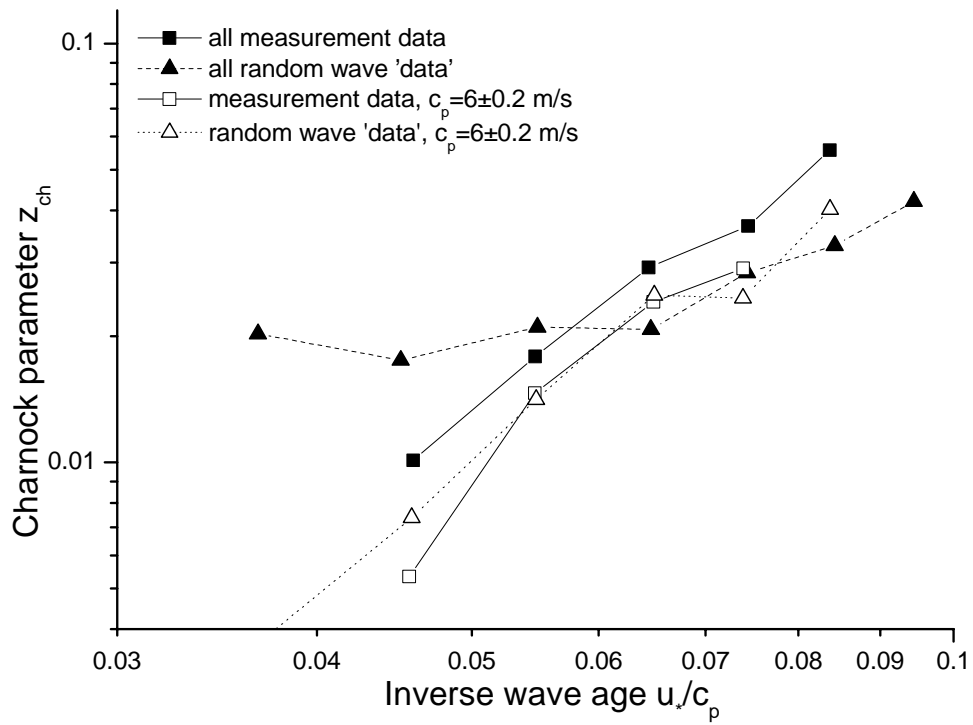


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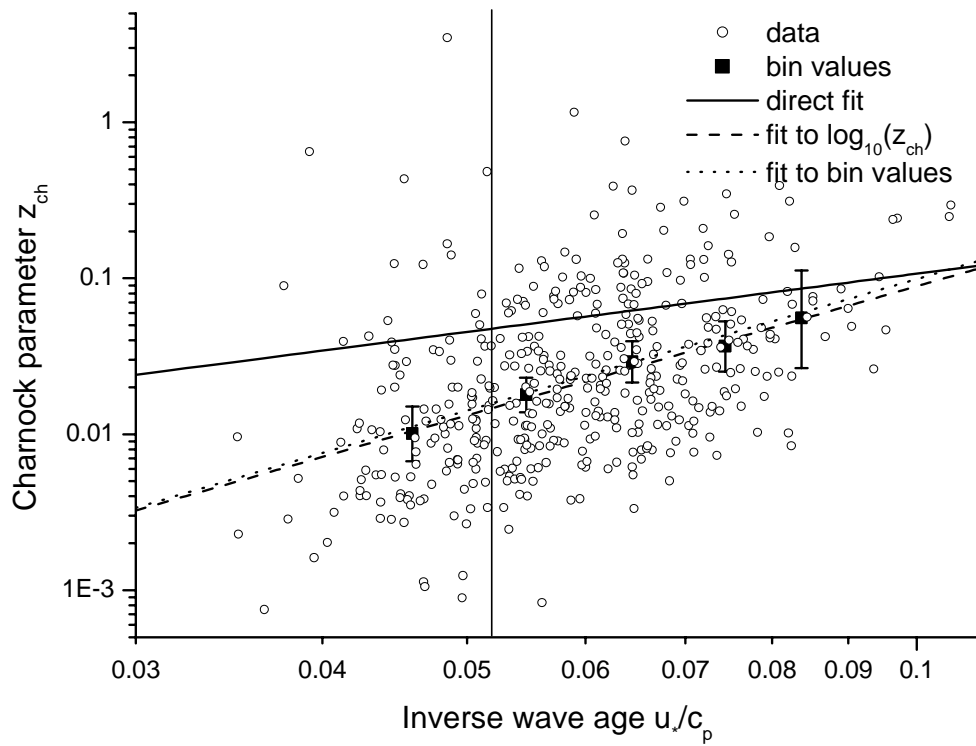


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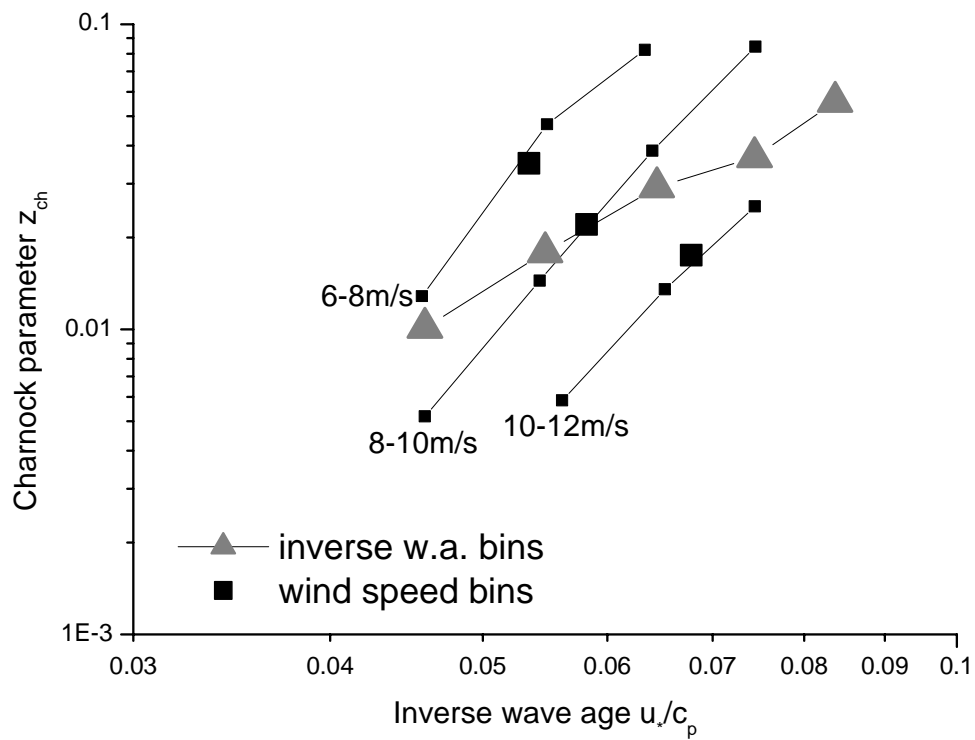


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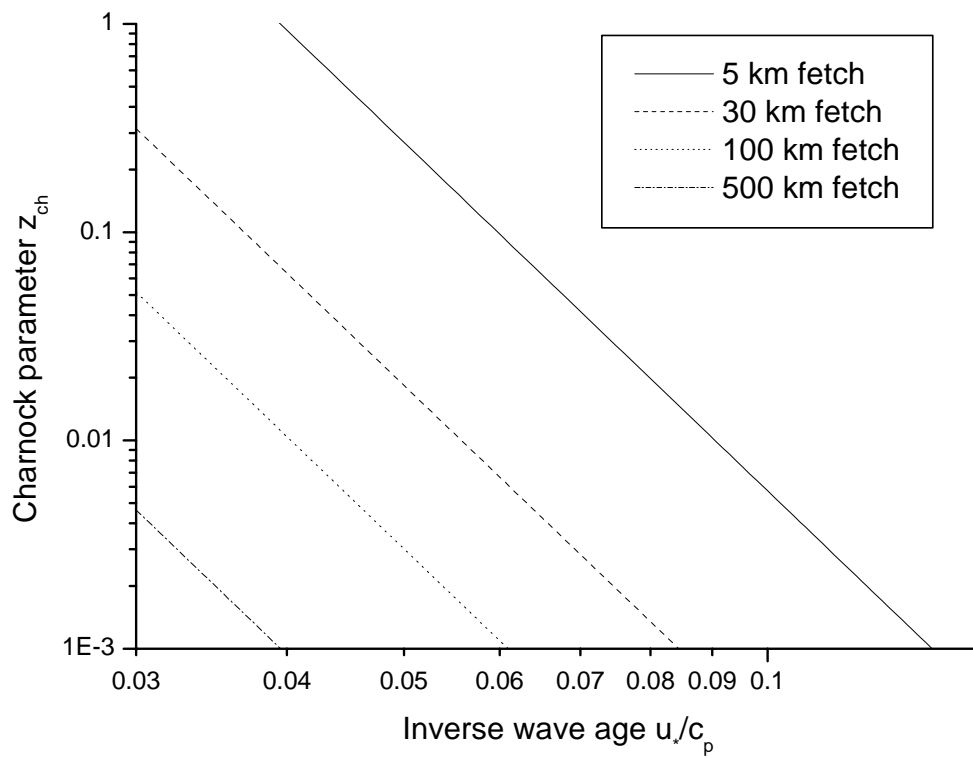


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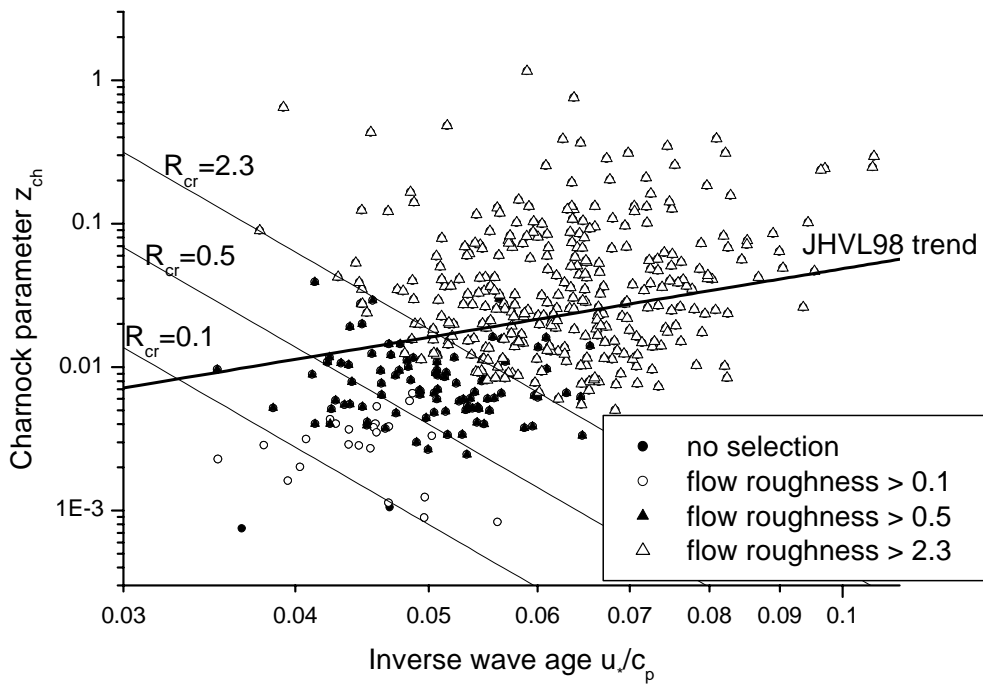


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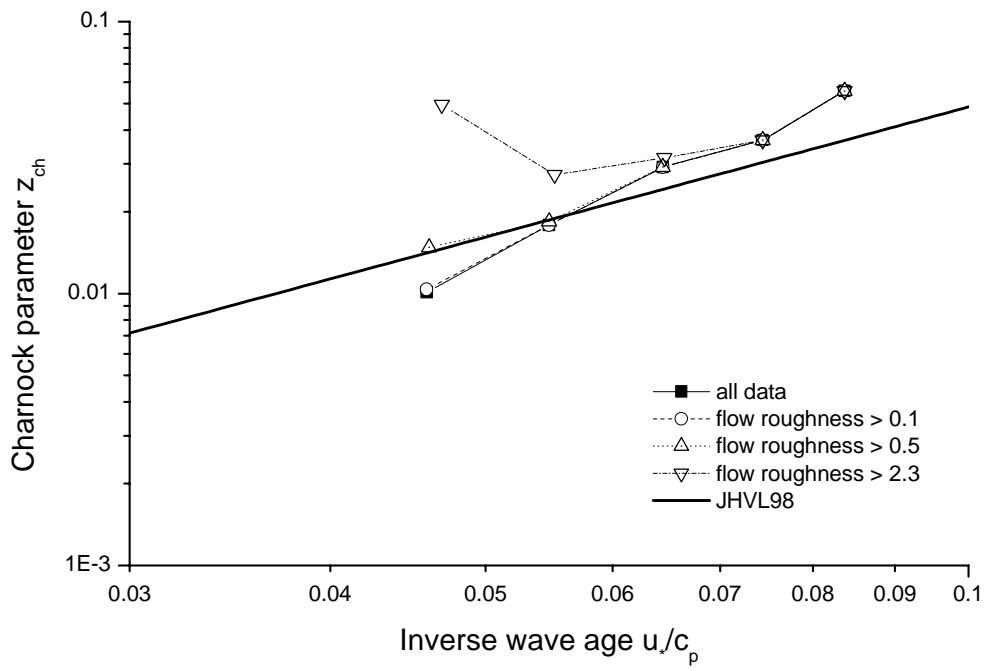


Figure 26: Charnock parameter versus inverse wave age for different flow roughness selection criteria

Table 1: Instrumentation of the Rødsand measurement

	height above mean sea level	instrument	sampling rate
Wind speed	50.3 m	cup anemometer	5 Hz
	29.8 m	cup anemometer	5 Hz
	10.2 m	cup anemometer	5 Hz
Wind direction	29.7 m	wind vane	5 Hz
3 axis wind speed and temperature	46.6 m (42.3 m from 12.5.99)	ultrasonic anemometer	20 Hz
Air temperature	10.0 m	Pt 100	30 min mean
Temperature difference	49.8 m – 10.0 m	Pt 500	30 min mean
Sea temperature		Pt 100	30 min mean
Sea level		DHI AWR201 acoustic wave recorder	8 Hz
Sea current		GMI current meter	8 Hz

Table 2: Selected wind direction sectors with approximately uniform fetch

Direction [°]	Name	Fetch [km]	number of records
200-230	Lübecker Bucht	60-90	102
240-260	Fehmarn	30-40	49
270-290	Femerbelt	>100	77
300-350	Lolland	10-20	50

Table 3: Parameter values proposed for the power law relation $z_{ch}=A(u_/c_p)^B$ in the literature*

	A	B
Toba et al., 1990	0.02	-0.5
Maat et al., 1991	0.8	1
Smith et al., 1992	0.48	1
Monbaliu, 1994	2.87	1.69
JHVL98	1.89	1.59
Drennan et al., 2003	1.7	1.7