

# Hearing devices using wireless acoustic sensor networks

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**<http://www.sigproc.uni-oldenburg.de>**

# Outline

- Use of multiple microphones in hearing devices
  - Monaural → Binaural → external microphones
- **Binaural signal processing**
  - Objective: noise reduction and binaural cue preservation
  - Algorithms: binaural beamforming, time-frequency masking, Multi-channel Wiener filter
  - Experimental results
  - Bandwidth reduction: iterative distributed MWF
- **Wireless acoustic sensor networks**
  - Algorithms: extension of distributed MWF
  - Effect of bitrate on performance
- Conclusions and future work

# Hearing aids

- Introduction

- Binaural processing

- Acoustic sensor networks

- Conclusion

- Problems: background noise, directional hearing
  - signal processing to selectively enhance useful speech signal and improve **speech intelligibility**
  - signal processing to preserve directional hearing (binaural auditory cues) and **spatial awareness**
- Digital hearing instruments allow for **advanced acoustical signal pre-processing**
  - multiple microphones available → spectral + spatial processing
  - noise reduction (beamforming), computational auditory scene analysis (source localisation, environment classification, ...)



*Monaural (2-3)*



*Binaural*

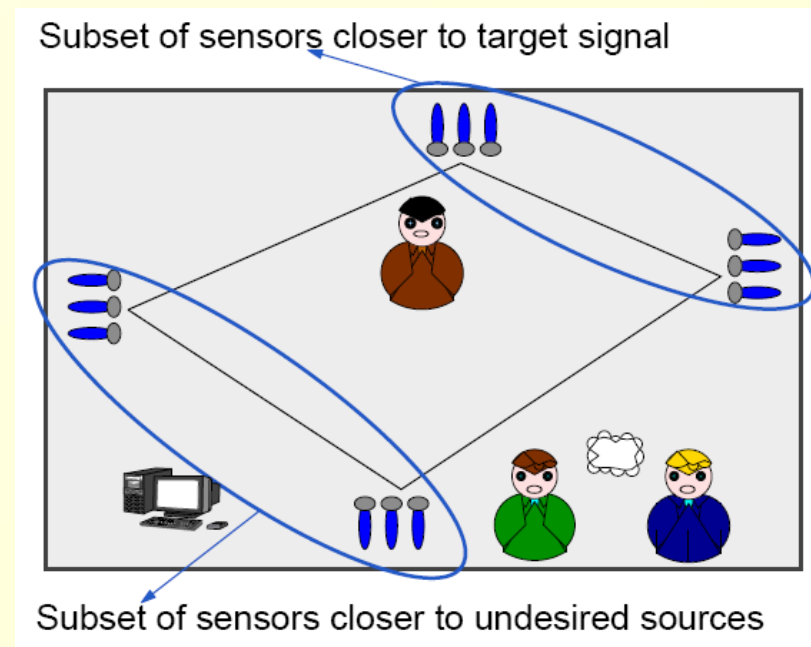


*External microphones*

# Acoustic sensor networks

- Introduction
- Binaural processing
- Acoustic sensor networks
- Conclusion

- Signal acquisition in **adverse acoustic environments**:
  - Microphones at large distance from speaker → background noise and reverberation
- **Acoustic sensor networks**:
  - Network of a large number of spatially distributed nodes (each with one or multiple microphones)
  - Wireless data transmission
  - More information about spatial noise field (microphones with higher SNR, direct-to-reverberant ratio)
- **Objectives**:
  - speech enhancement
  - source localisation
  - CASA



# Acoustic sensor networks

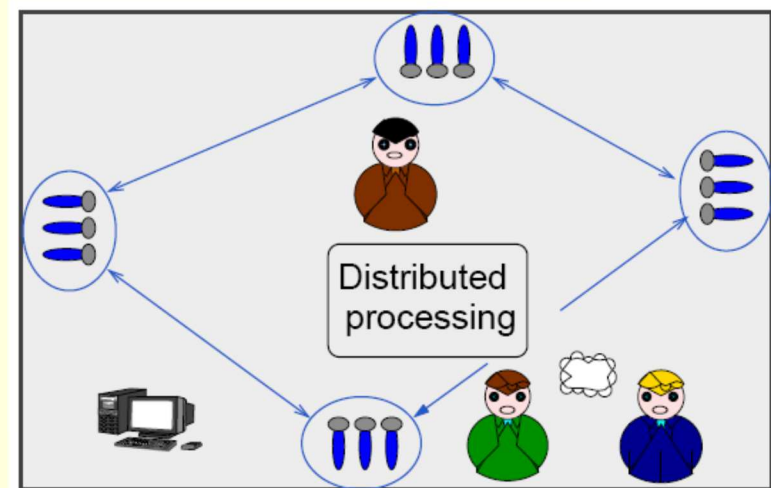
- Introduction
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- **Challenges:**

- o *Dynamic array configuration:* large number of microphones at unknown positions, dynamic subset selection
- o *Distributed and collaborative algorithms:* power and complexity constraints, effect of limited bandwidth
- o *Calibration and synchronisation issues:* same time basis

- **Prototype applications:**

- o Hearing aids using extra microphones (room, other HA, ...)
- o Video-conferencing using all microphones on laptops / room
- o Surveillance

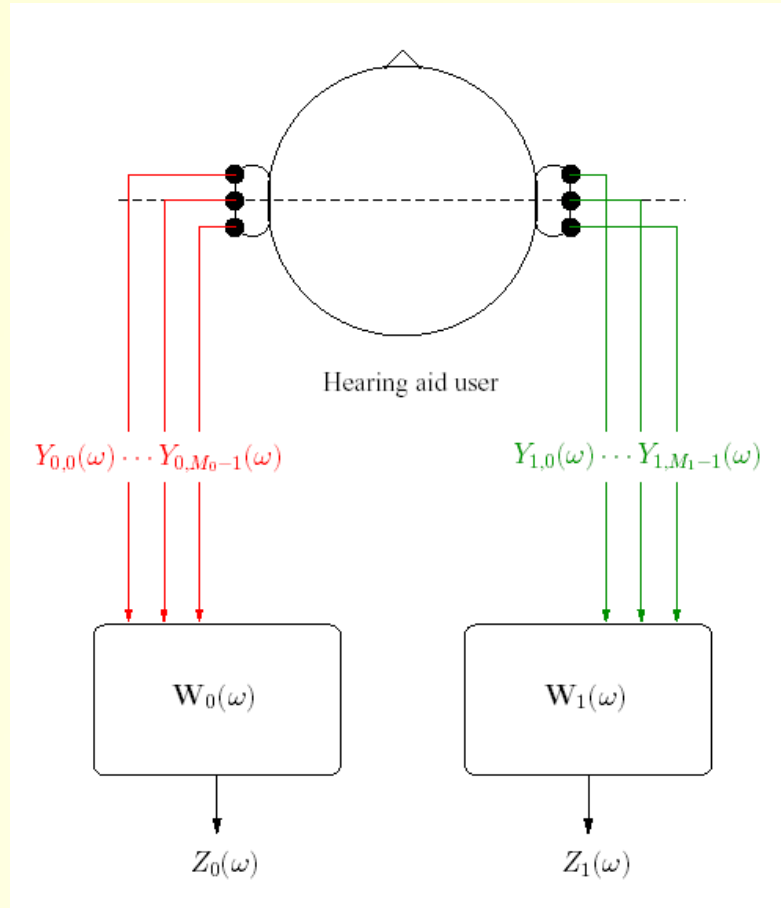


# Binaural processing

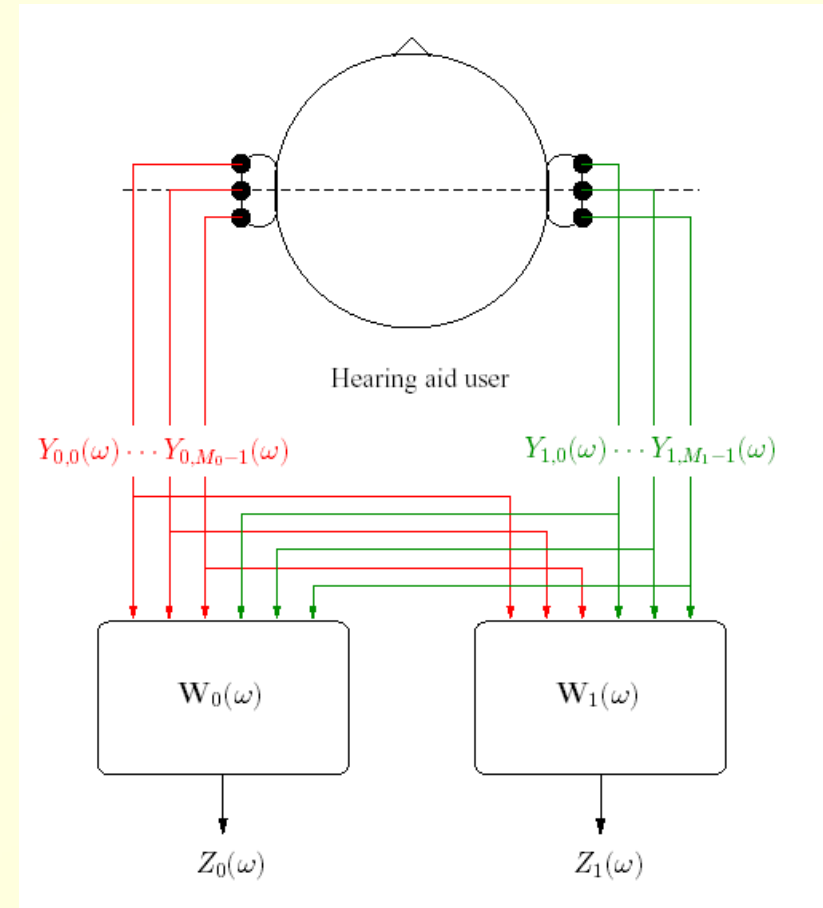
# Bilateral vs. Binaural

- Introduction
- Binaural processing
  - Algorithms
  - Experiments
  - Distributed MWF
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Bilateral system



Binaural system



⊖ Independent left/right processing:  
 Preservation of binaural cues  
 (ILD/ITD) for localisation ?

⊕ More microphones:  
 → better performance ?  
 → preservation of binaural cues ?

⊖ Need for wireless binaural link 7

# Bilateral vs. Binaural

- Introduction

- Binaural processing

  - Algorithms

  - Experiments

  - Distributed MWF

- Acoustic sensor networks

- Conclusion

- Bilateral system

  - o Independent processing of left and right hearing aid
  - o Negative effect on localisation cues and intelligibility through binaural hearing advantage [Van den Bogaert et al., 2006]

- Binaural system

  - o Cooperation between left and right hearing aid (e.g. wireless link) → **centralised** vs. **distributed** processing
  - o Bandwidth constraint and latency of wireless link

## Objectives/requirements for binaural algorithm:

1. SNR improvement: noise reduction, limit speech distortion
2. Preservation of binaural cues (all sources) to exploit binaural hearing advantage
3. No assumption about position of speech source and microphones



# Binaural noise reduction techniques

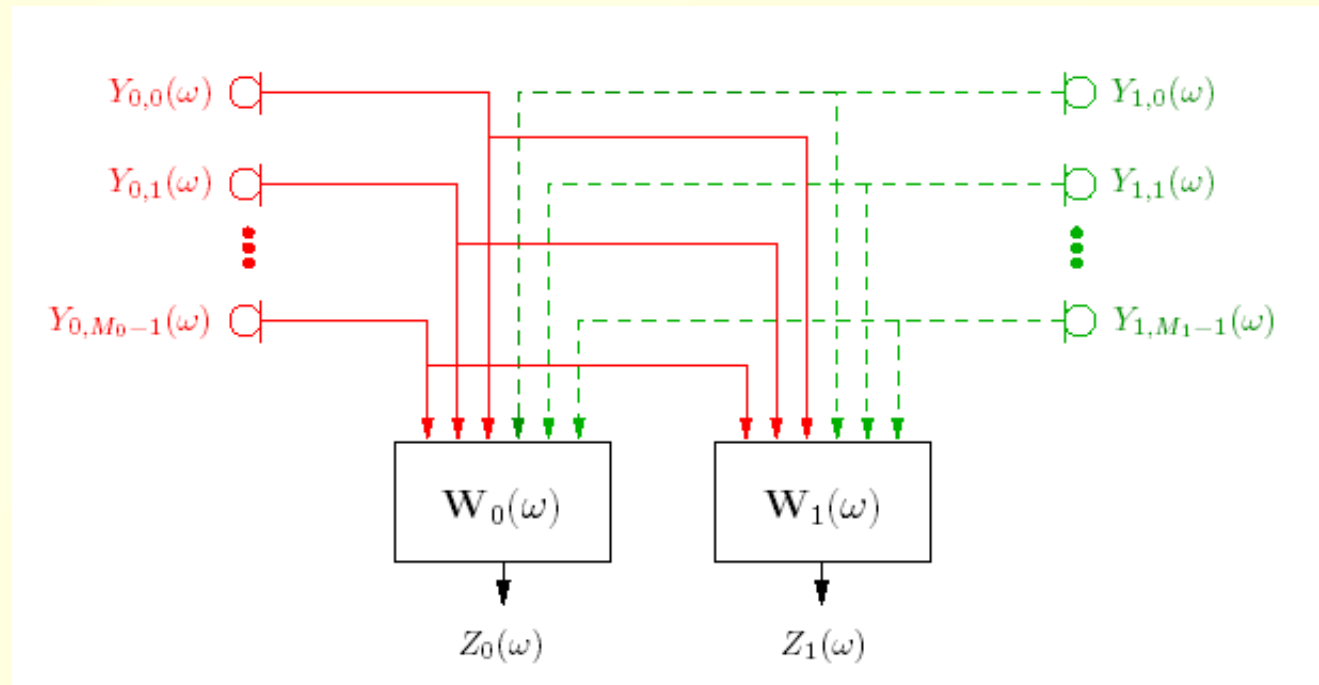
- Introduction
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- **Configuration:** microphone array with  $M$  microphones at left and right hearing aid, communication between hearing aids

$$Y_{0,m}(\omega) = \underset{\substack{\uparrow \\ \text{speech}}}{X_{0,m}(\omega)} + \underset{\substack{\uparrow \\ \text{noise}}}{V_{0,m}(\omega)}, \quad m = 0 \dots M_0 - 1$$

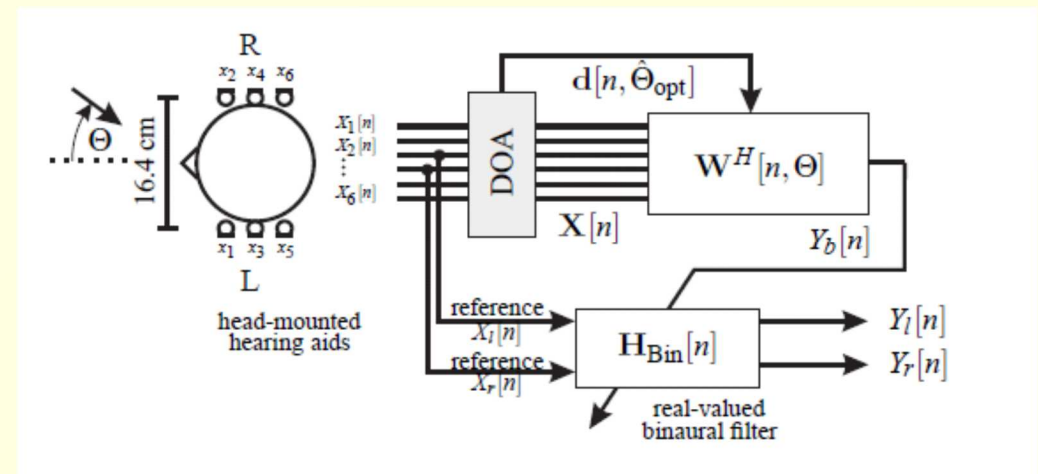
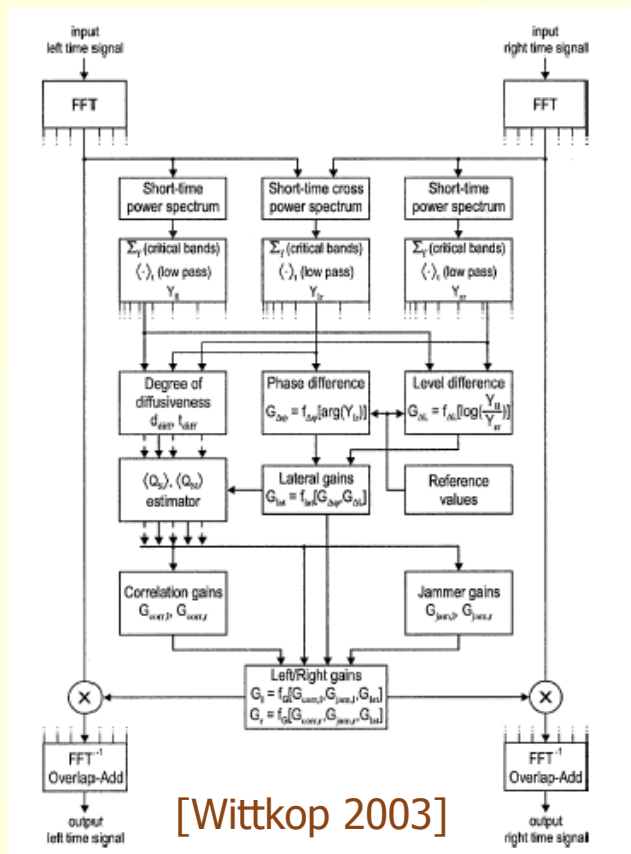
- Use all microphone signals to compute **output signal at both ears**

$$Z_0(\omega) = \mathbf{W}_0^H(\omega)\mathbf{Y}(\omega), \quad Z_1(\omega) = \mathbf{W}_1^H(\omega)\mathbf{Y}(\omega)$$



# Binaural noise reduction techniques

- Introduction
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- Time-frequency post-processing/masking:
    - Computation and application of **real-valued** binaural mask based on binaural and temporal/spectral cues
    - Can be merged with MVDR-beamformer or ICA-based processing
    - ⊕ Good preservation of binaural cues for **all** sources
    - ⊖ “single-microphone spectral enhancement” artefacts at low SNRs



$$\text{Beamformer: } \mathbf{W}_b = \frac{\Gamma^{-1} \mathbf{d}}{\mathbf{d}^H \Gamma^{-1} \mathbf{d}} \Rightarrow \mathbf{Y}' = \mathbf{W}_b^H \mathbf{Y}$$

$$\text{Post-Filter: } H_p = \frac{(|d_0|^2 + |d_1|^2) |Y'|^2}{|Y_0|^2 + |Y_1|^2} \Rightarrow \mathbf{Z} = H_p \begin{bmatrix} Y_0 \\ Y_1 \end{bmatrix}$$

[Rohdenburg 2009, Reindl 2010, Saruwatari 2010]

# Binaural noise reduction techniques

- Binaural multi-channel Wiener filter: estimate of speech component in microphone signal at both ears (usually front mic) + trade-off between noise reduction and speech distortion

$$J(\mathbf{W}) = E \left\{ \left\| \begin{bmatrix} X_{0,r_0} - \mathbf{W}_0^H \mathbf{X} \\ X_{1,r_1} - \mathbf{W}_1^H \mathbf{X} \end{bmatrix} \right\|^2 + \mu \left\| \begin{bmatrix} \mathbf{W}_0^H \mathbf{V} \\ \mathbf{W}_1^H \mathbf{V} \end{bmatrix} \right\|^2 \right\} \rightarrow \mathbf{W}_{SDW} = \mathbf{R}^{-1} \mathbf{r}$$

speech component in front microphones      speech distortion      noise reduction

$$\mathbf{R} = \begin{bmatrix} \mathbf{R}_x + \mu \mathbf{R}_v & \mathbf{0}_M \\ \mathbf{0}_M & \mathbf{R}_x + \mu \mathbf{R}_v \end{bmatrix}, \quad \mathbf{r} = \begin{bmatrix} \mathbf{r}_{x0} \\ \mathbf{r}_{x1} \end{bmatrix}, \quad \mathbf{R}_x = \mathbf{R}_y - \mathbf{R}_v \quad \text{estimate}$$

- o Estimate  $\mathbf{R}_y$  during speech-dominated time-frequency segments, estimate  $\mathbf{R}_v$  during noise-dominated segments, requiring robust voice activity detection (VAD) mechanism
- o No assumptions about positions of microphones and sources
- o Different implementations:
  - Batch (off-line) vs. adaptive (update correlation matrices)
  - Using spatial prediction (SP) between speech components [Chen 2008]

• Introduction

• Binaural processing

-Algorithms

-Experiments

-Distributed MWF

• Acoustic sensor networks

• Conclusion

[S. Doclo, S. Gannot, M. Moonen, A. Spriet, Handbook on Array Processing and Sensor Networks, Wiley, 2010.]

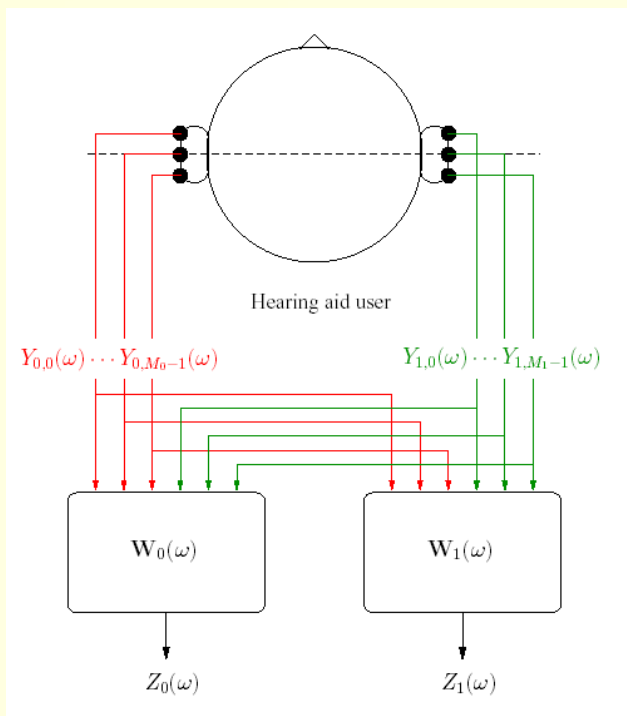
[B. Cornelis, S. Doclo, T. Van den Bogaert, J. Wouters, M. Moonen, IEEE Trans. Audio, Speech and Language Processing, Feb. 2010.]

[S. Doclo, T.J. Klase, M. Moonen, T. Van den Bogaert, J. Wouters, R.P. Derleth, S. Korl, US2010002886.]

# Binaural noise reduction techniques

- Introduction
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  - Algorithms
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- Binaural multi-channel Wiener filter:
  - o Preservation of binaural cues (ITD-ILD)
    - Speech cues are preserved, no a-priori assumptions
    - **Noise cues are distorted**
  - o **Extensions** in order to preserve binaural cues of both speech and noise sources, without substantially compromising noise reduction
    - Partial noise estimation (MWFv)
    - Extension with Interaural Transfer Function (MWF-ITF)



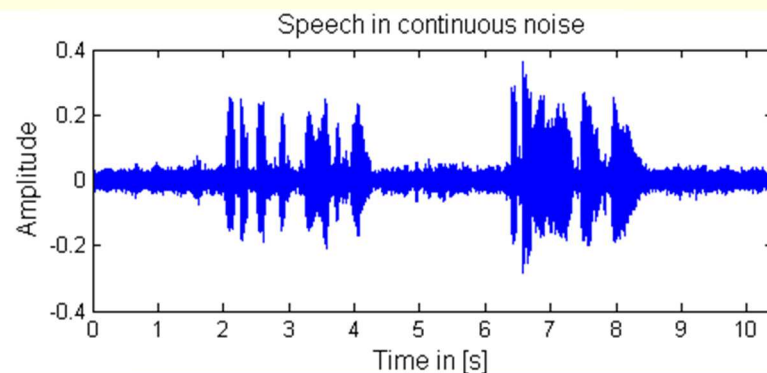
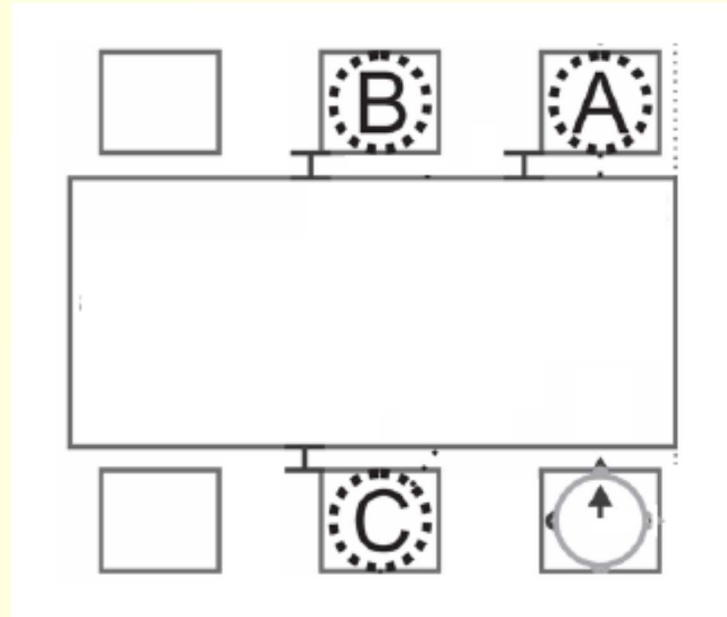
$$J_{SDW\eta}(\mathbf{W}) = E \left\{ \left\| \begin{bmatrix} X_L - \mathbf{W}_L^H \mathbf{X} \\ X_R - \mathbf{W}_R^H \mathbf{X} \end{bmatrix} \right\|^2 + \mu \left\| \begin{bmatrix} \eta \mathbf{V}_L - \mathbf{W}_L^H \mathbf{V} \\ \eta \mathbf{V}_R - \mathbf{W}_R^H \mathbf{V} \end{bmatrix} \right\|^2 \right\}, \quad 0 \leq \eta \leq 1$$

$$J_{ITF}(\mathbf{W}) = J_{SDW}(\mathbf{W}) + \alpha E \left\{ \left| \mathbf{W}_L^H \mathbf{X} - ITF_{in}^x \mathbf{W}_R^H \mathbf{X} \right|^2 \right\} + \beta E \left\{ \left| \mathbf{W}_L^H \mathbf{V} - ITF_{in}^y \mathbf{W}_R^H \mathbf{V} \right|^2 \right\}$$

# Experimental results

- Introduction
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- **Acoustic environment**



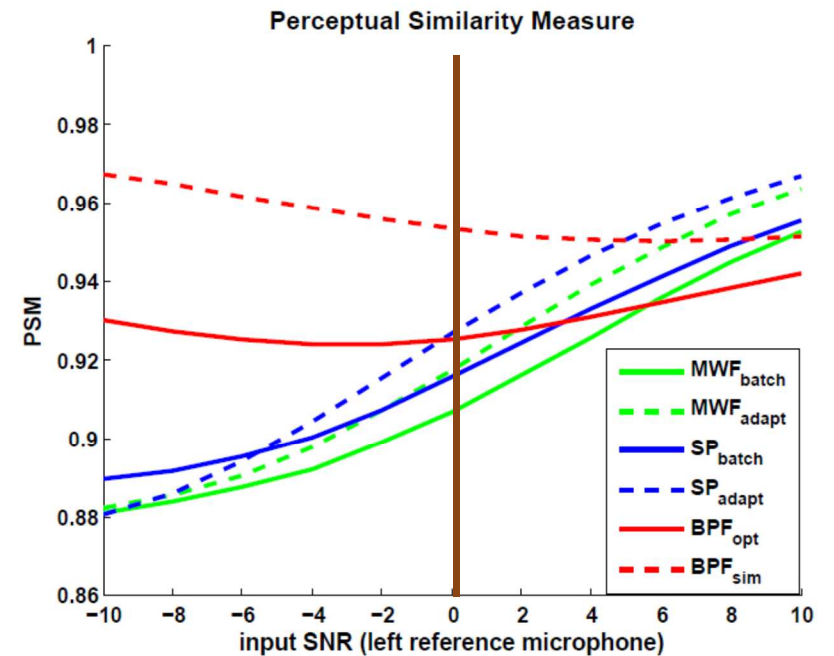
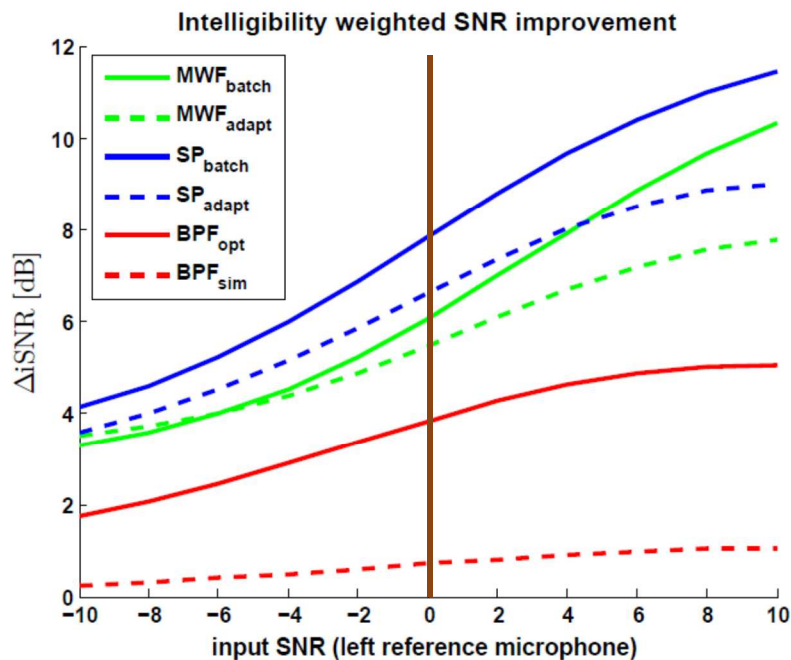
- Cafeteria with recorded babble noise and simulated speaker at position B
- Binaural hearing aid with 3 microphones
- German sentences taken from OLSA speech material
- Speech in continuous babble noise
- $f_s$ : 16 kHz, WOLA, FFT-size: 256 samples, Overlap: 75%



<http://medi.uni-oldenburg.de/hrir/> [Kayser et al. 2009]

# Experimental results

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- **Objective Evaluation**
  - Intelligibility weighted SNR improvement
  - Perceptual Similarity Measure (PSM)



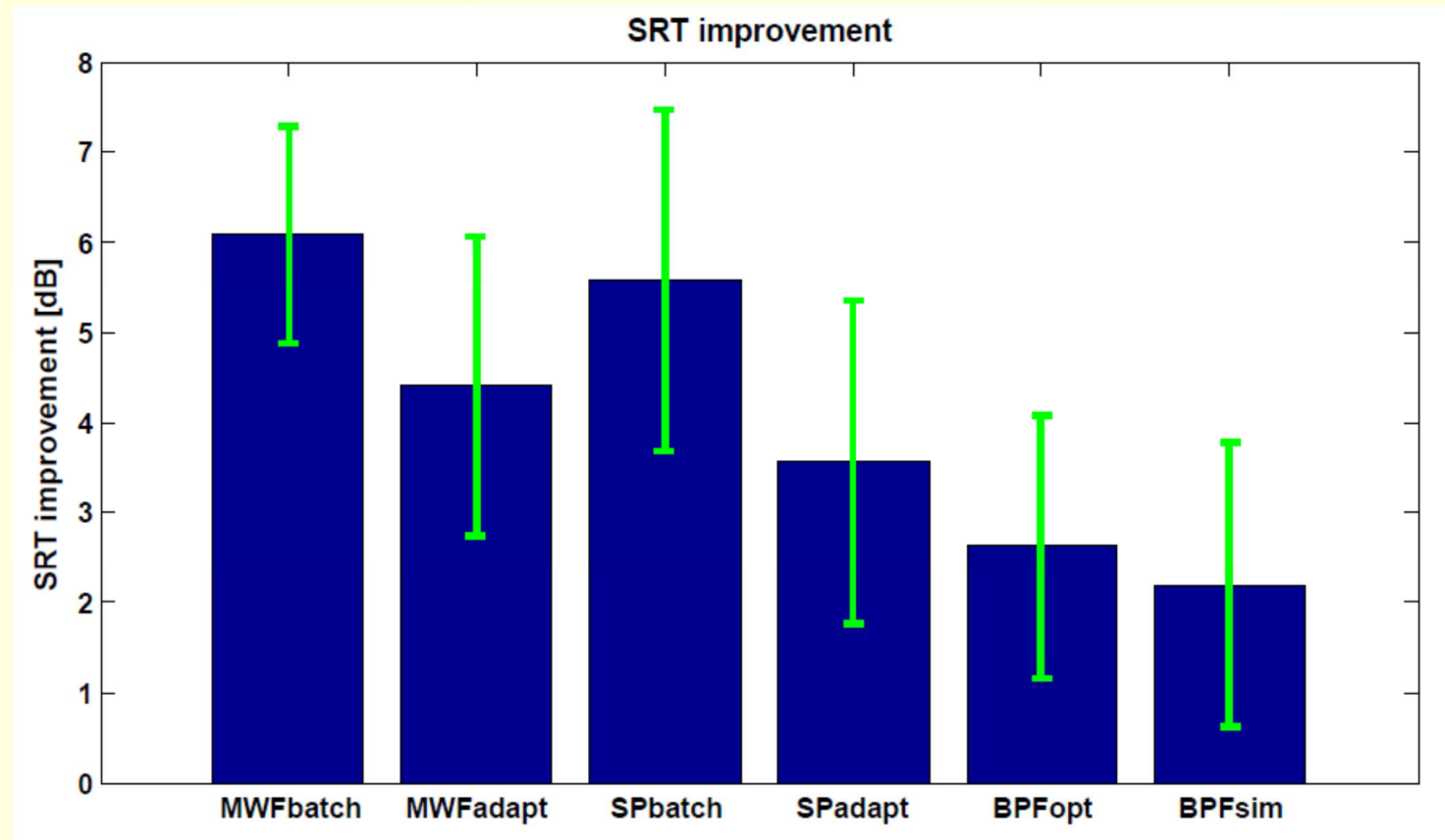
| SNR  | Orig.   | MWF   | SP  | BF + Postfilt   |
|------|---|---|---|---|
| 0 dB |  |  |  |  |

# Experimental results

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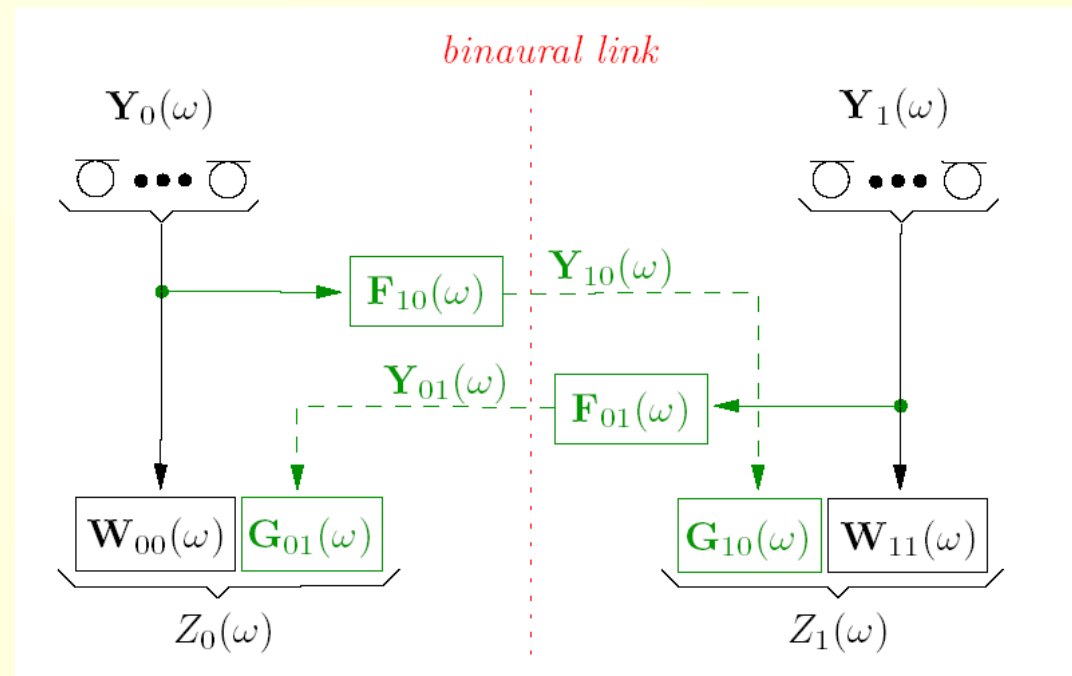
- **Subjective Evaluation**

- o Improvement of Speech Reception Threshold (SRT)
- o Oldenburg Sentence Test (10 NH subjects)
- o Binaural presentation using headphones



# Distributed MWF

- Binaural MWF
  - **all** microphone signals are transmitted over wireless link
- Reduce **bandwidth requirement** of wireless link by transmitting **one** signal from contralateral ear
  - Raw microphone signal (e.g. front)
  - Output of fixed (e.g. superdirective) beamformer
  - MWF-estimate using only contralateral microphone signals
  - **Iterative distributed binaural MWF scheme (DB-MWF)**

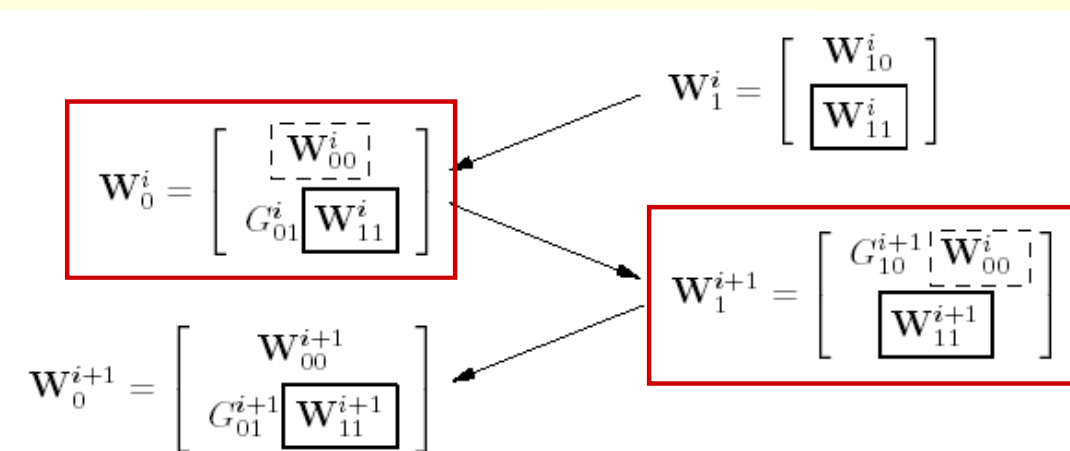
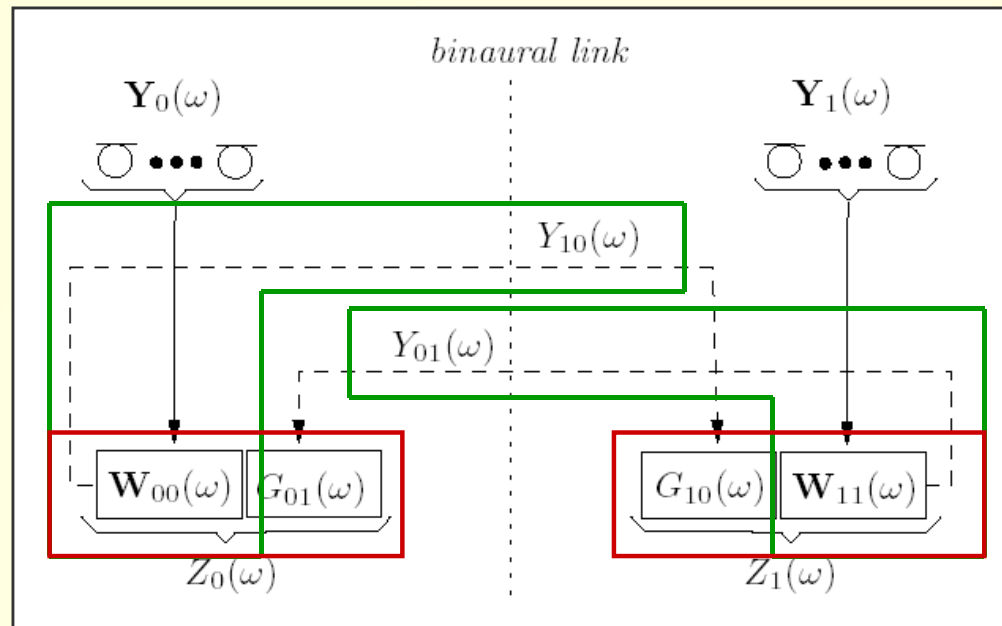




# Distributed MWF

- Iterative procedure

- In each iteration  $\mathbf{F}_{10}$  is equal to  $\mathbf{W}_{00}$  from previous iteration, and  $\mathbf{F}_{01}$  is equal to  $\mathbf{W}_{11}$  from previous iteration



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# Distributed MWF

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- Single speech source

- o MWF cost function decreases in each step of iteration

$$J\left(\begin{bmatrix} \mathbf{W}_0^{i+1} \\ \mathbf{W}_1^{i+1} \end{bmatrix}\right) \leq J\left(\begin{bmatrix} \mathbf{W}_0^i \\ \mathbf{W}_1^i \end{bmatrix}\right)$$

- o Remarkably: convergence to B-MWF solution (!)



$$\mathbf{W}_0^\infty = \mathbf{W}_0^m, \quad \mathbf{W}_1^\infty = \mathbf{W}_1^m$$

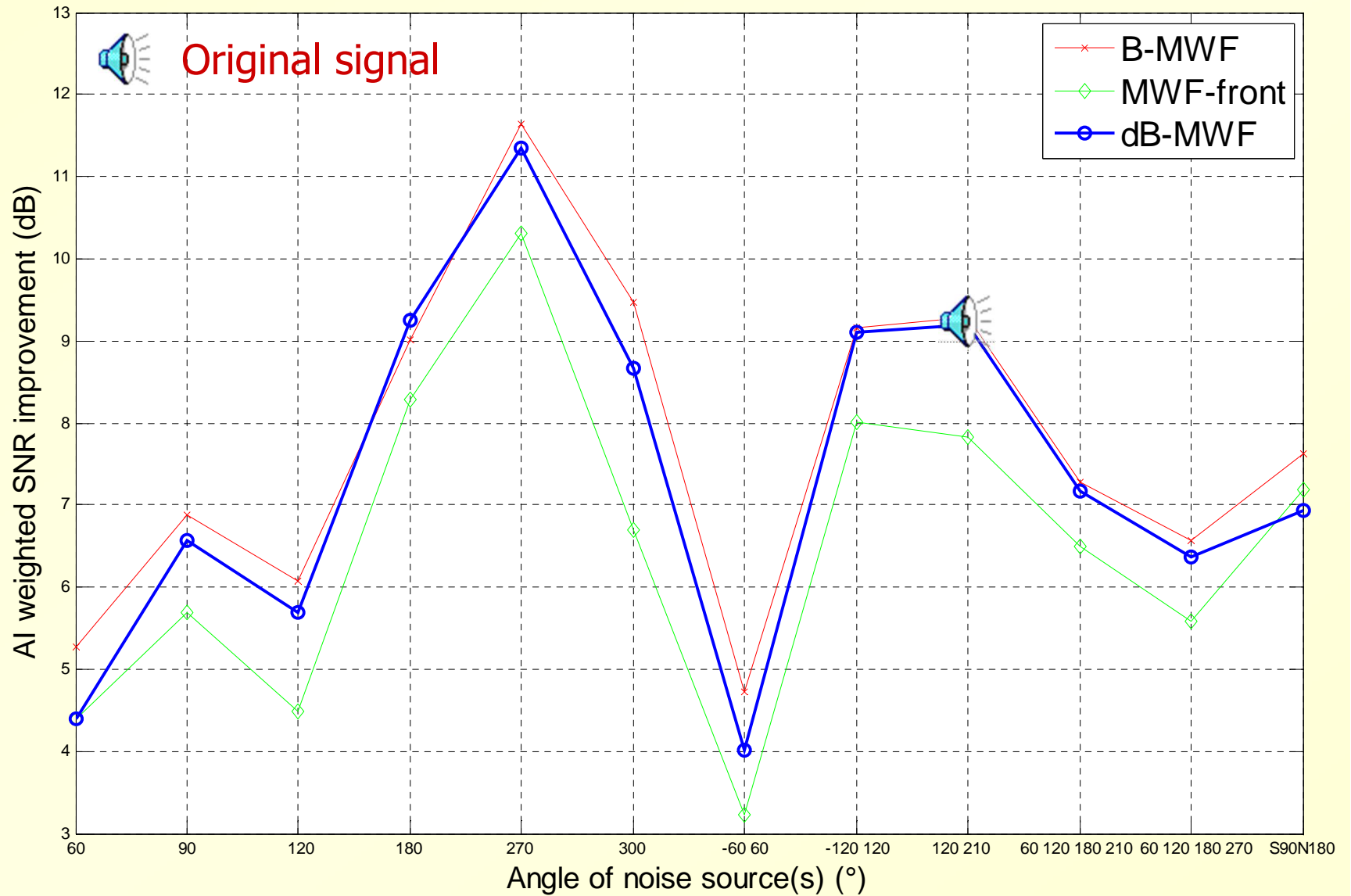
- General case where  $\mathbf{R}_x$  is not a rank-1 matrix

- o MWF cost function does not necessarily decrease in each iteration
- o usually no convergence to optimal B-MWF solution
- o Although  $J_0(\mathbf{W}_0^\infty) \geq J_0(\mathbf{W}_0^m)$ ,  $J_1(\mathbf{W}_1^\infty) \geq J_1(\mathbf{W}_1^m)$ , DB-MWF procedure can be used in practice and approaches binaural MWF performance

# Distributed MWF

Performance comparison (left,  $L=128$ ,  $T_{60}=500$  ms)

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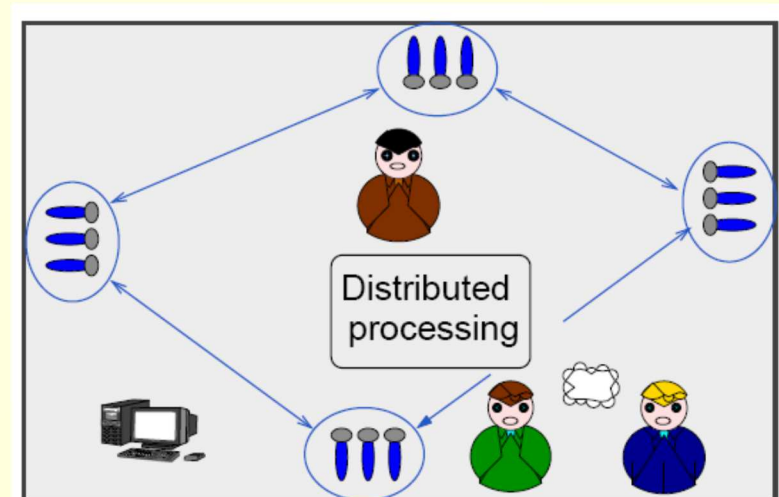
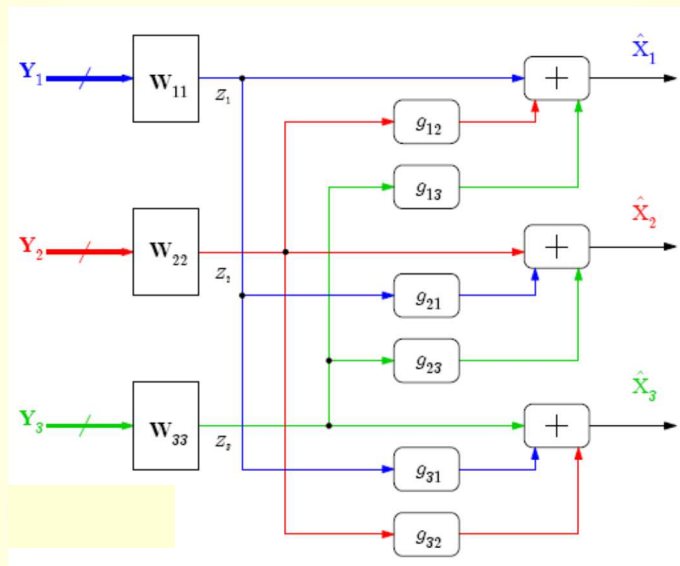
Real-world performance of db-MWF close to full binaural MWF !

# Acoustic sensor networks

# Acoustic sensor networks

- Introduction
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  - Rate constraints
  - Future work
- Conclusion

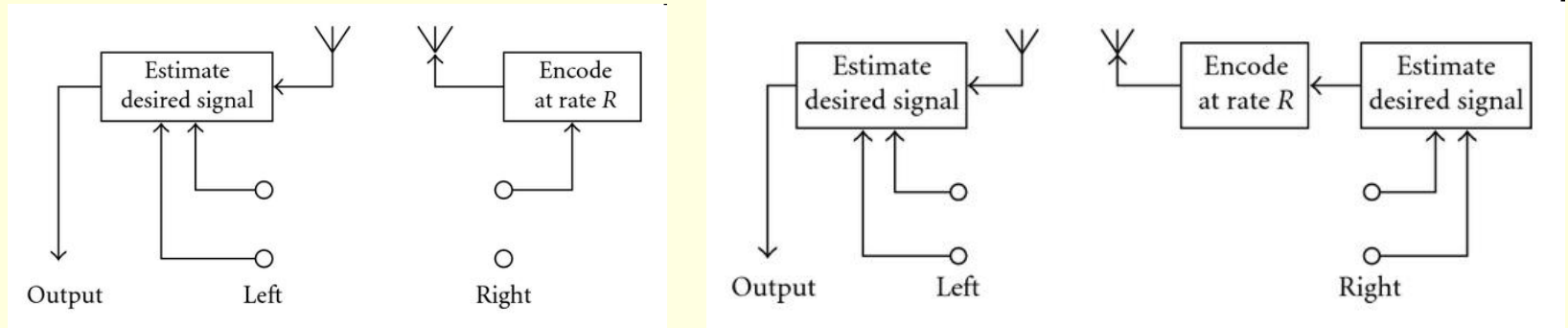
- Now consider more than 2 sensor nodes...
- Recently has become quite a **hot research topic**
  - o Distributed MWF: extension to multiple sensor arrays and multiple desired sources (DANSE) [Bertrand 2010]
  - o Distributed MVDR/LCMV-beamformer [Golan 2010, Bertrand 2011]
  - o Performance analysis of a randomly spaced wireless microphone array [Golan 2011]
  - o Dynamic signal combining (no synchronisation required) [Matheja 2011, Srinivasan 2011, Stenger 2011]



# Rate constraints

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- Investigate effect of **capacity of wireless link** → encode signal(s) at finite bit-rate  $R$  before transmission



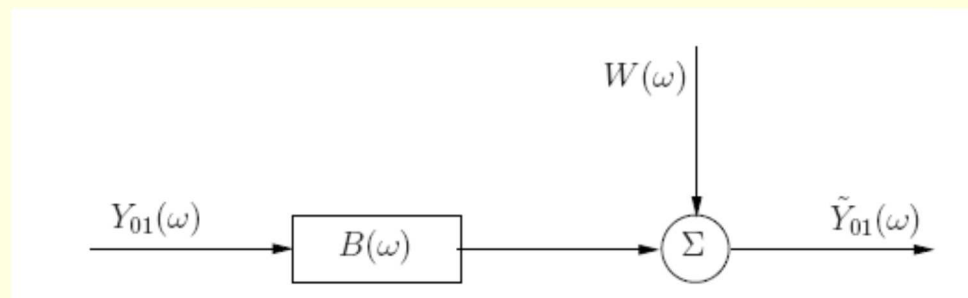
- **Rate-distortion:**

$$R(\lambda) = \frac{1}{4\pi} \int_{-\infty}^{\infty} \max \left( 0, \log_2 \frac{\Phi_Y^{01}(\omega)}{\lambda} \right) d\omega$$

$$D(\lambda) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \min \left( \lambda, \Phi_Y^{01}(\omega) \right) d\omega,$$

PSD of transmitted signal

- Upper bound on achievable performance can be calculated using **forward channel representation**



$$B = \max \left( 0, \frac{\Phi_Y^{01} - \lambda}{\Phi_Y^{01}} \right)$$

$$\Phi_W = \max \left( 0, \lambda \frac{\Phi_Y^{01} - \lambda}{\Phi_Y^{01}} \right)$$

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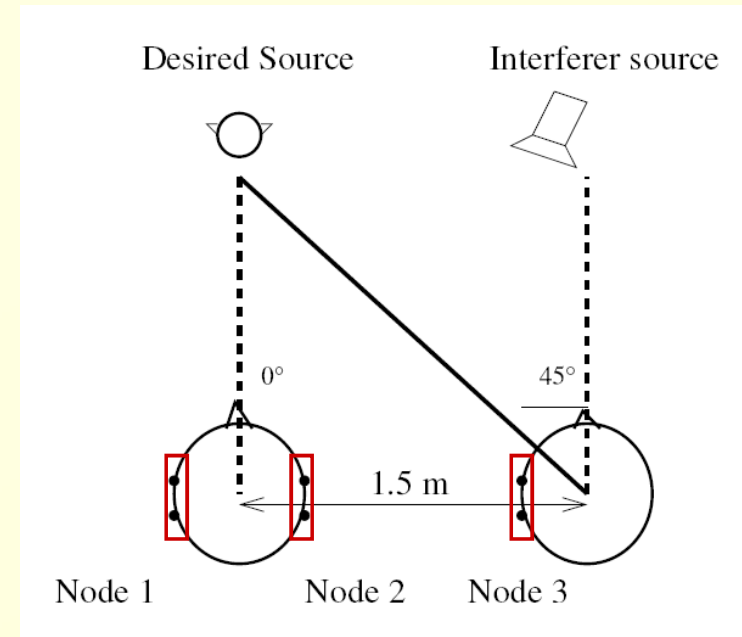
- Investigate effect of rate constraints on performance of centralized MWF and distributed MWF (DANSE)

- Setup and performance measures:

- o **Acoustic scenario:** 3 nodes, 2 microphones per node ( $d=1\text{cm}$ )
- o single speech source, single interference, spatially uncorrelated noise on each microphone

$$\Phi_y = \Phi_s \mathbf{A}_s \mathbf{A}_s^H + \Phi_i \mathbf{A}_i \mathbf{A}_i^H + \Phi_u \mathbf{I}_{2M}$$

- Involved PSDs are assumed to be flat, SIR=0 dB, SNR=20 dB
- ATFs modelled using spherical head shadow model, no reverberation
- o **Performance measure:** ratio between MSE at rate 0 and MSE at rate  $R$ , *i.e.* effect of availability of wireless link

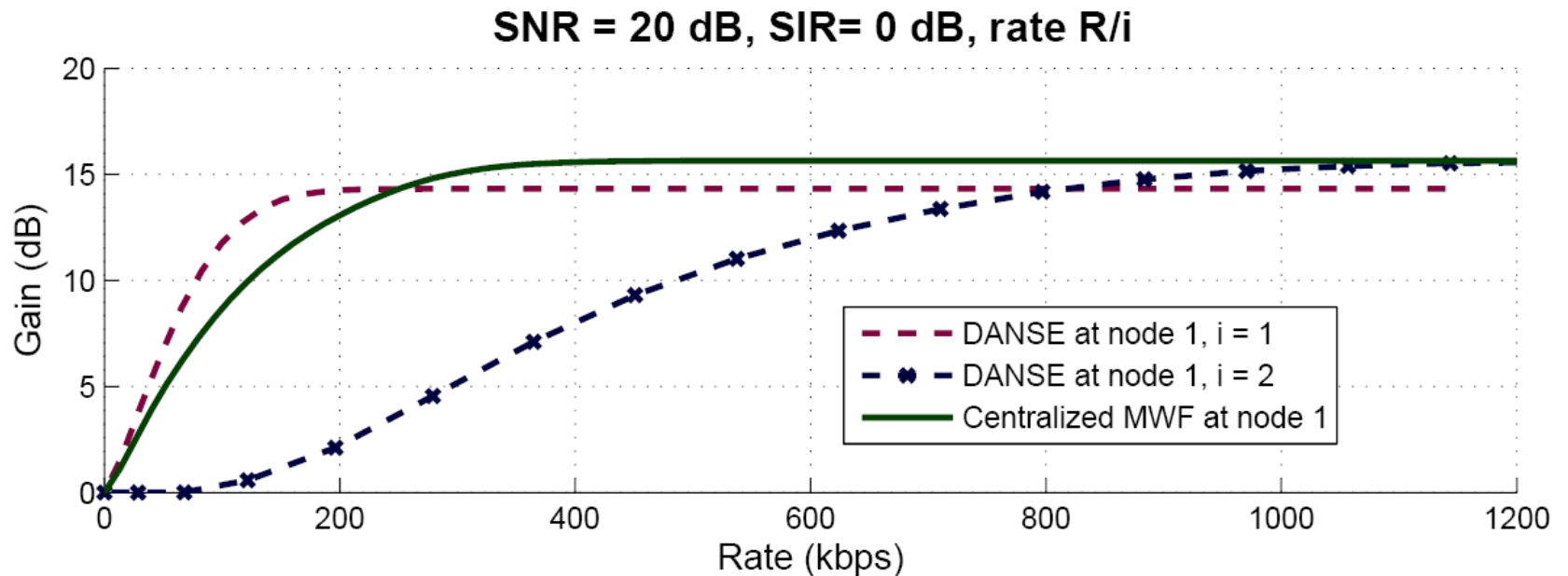


$$G(R) = 10 \log_{10} \frac{\xi(0)}{\xi(R)}$$

# Rate constraints

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- Effect on performance of **distributed MWF (DANSE)**
  - **Case 1:** total capacity  $R$  evenly distributed between iterations



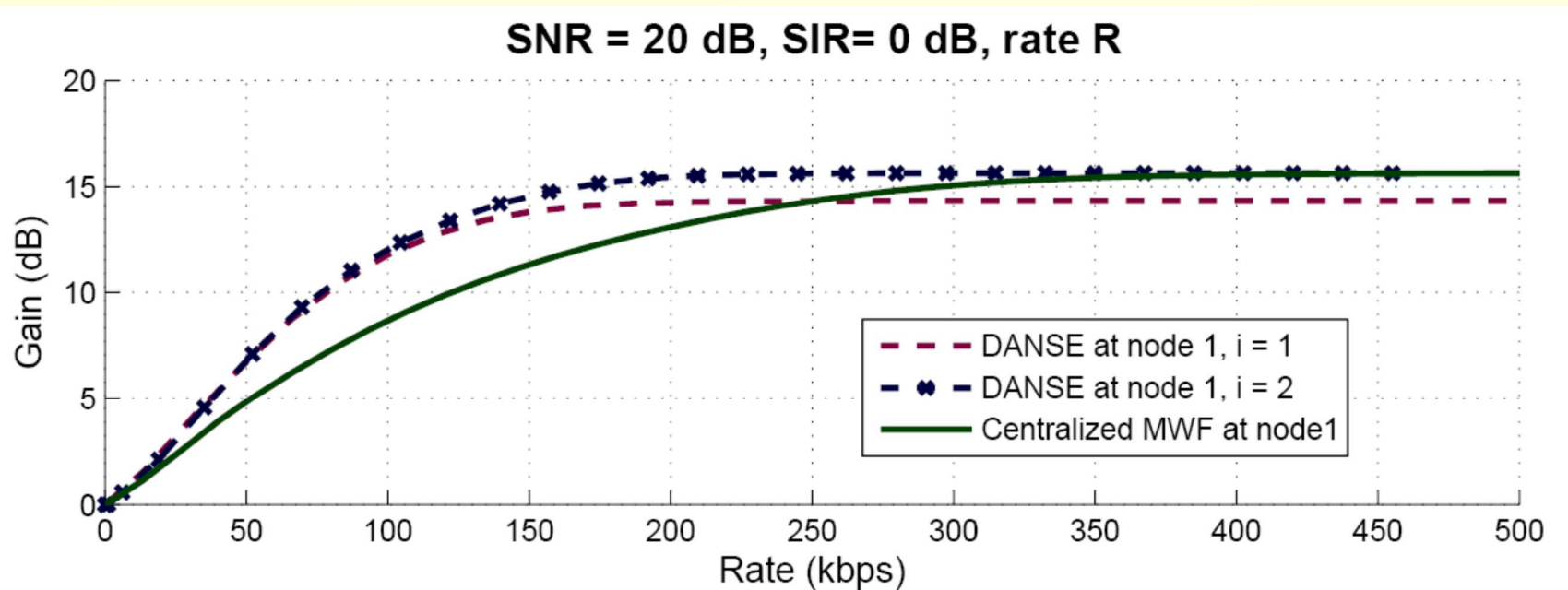
- For **infinite rate**, DANSE converges to centralized MWF
- At **low rates** highest performance gain is achieved by transmitting just a single microphone signal ( $i = 1$ ).
- **More iterations** only improve performance at high rates



# Rate constraints

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- Effect on performance of **distributed MWF (DANSE)**
  - **Case 2:** spread iterations over subsequent frames (stationarity)



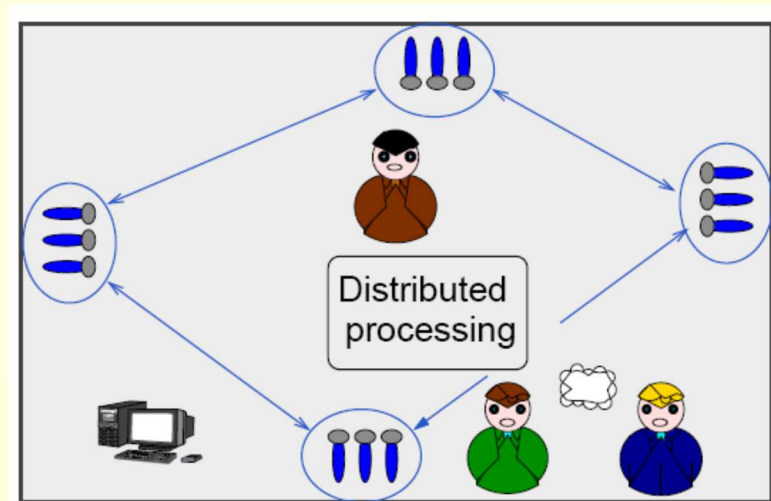
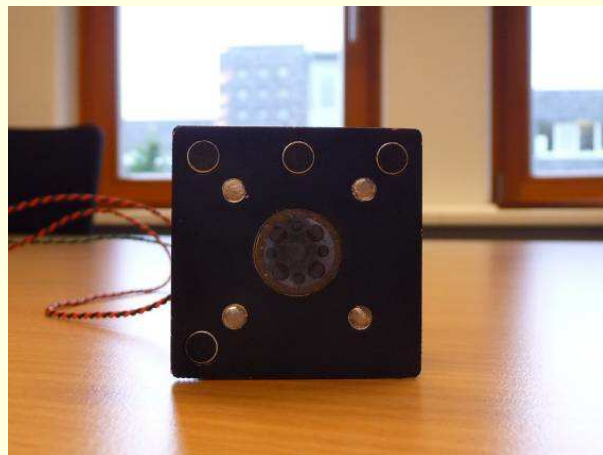
- **DANSE scheme** converges after  $i=2$  iterations, moreover achieving **highest performance gain**

# Acoustic sensor networks

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- **Future work/challenges:**

- o *Speech enhancement algorithms:*
  - Dynamic subset selection for time-varying situations
  - Theoretical performance analysis (statistical room acoustics)
    - optimal microphone configuration
- o *Computational auditory scene analysis:*
  - E.g. multi-source localisation by merging energy- and correlation-based techniques
- o *Calibration and synchronisation techniques:*
  - With and without reference signals
- o (Perceptual) *coding* of transmitted signals



# Conclusions

- Introduction
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- Speech enhancement algorithms in **hearing instruments**
  - More and more microphones: monaural → binaural → acoustic sensor networks
  - Algorithms: beamforming, post-processing, MWF
- **Bandwidth reduction** by transmitting filtered combination of microphone signals
  - D-MWF: iterative procedure, converging to centralized MWF
- Effect of **bit-rate** on performance using rate-distortion theory
  - D-MWF achieves highest performance gain, when iterations can be spread over subsequent frames
- Remaining **challenges in acoustic sensor networks**:
  - **Algorithms**: robustness, dynamic subset selection, distributed algorithms, optimal microphone configuration
  - **(Perceptual) coding** of transmitted signal
  - **Technical issues of wireless link**: latency, synchronisation

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Questions ?



***House of Hearing, Oldenburg***